

### Question 8

If  $T$  is a standard maximal torus in  $G$ , the roots of  $G$  are computed by considering the adjoint action,

$$Ad(t)e_i \quad (t \in T)$$

where  $\{e_i\}$  is a basis for  $L(G)$ .

Given  $\gamma_i(u)$  a one-parameter subgroup in  $G$  such that  $\gamma'_i(0) = e_i$ ,  $Ad(t)$  is the differential of the map

$$A(t) : g \rightarrow t g t^{-1},$$

so  $Ad(t)(\gamma'_i(0)) = (t\gamma_i(u)t^{-1})' = te_it^{-1}$ .

We may thus directly evaluate the  $Ad(t)(e_i)$  on the given basis  $\{e_i\}$ . Writing an element  $t \in T$  as

$$t = \begin{bmatrix} e^{i\theta_1} & & \\ & e^{i\theta_2} & \\ & & e^{i\theta_3} \end{bmatrix}, \text{ where } \theta_3 = -(\theta_1 + \theta_2)$$

we compute  $te_1t^{-1} = e_1$ ,  $te_2t^{-1} = e_2$ .

$$\begin{aligned} \text{Now } te_3t^{-1} &= \begin{bmatrix} e^{i\theta_1} & 0 & 0 \\ 0 & e^{i\theta_2} & 0 \\ 0 & 0 & e^{i\theta_3} \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} e^{-i\theta_1} & 0 & 0 \\ 0 & e^{-i\theta_2} & 0 \\ 0 & 0 & e^{-i\theta_3} \end{bmatrix} \\ &= \begin{bmatrix} 0 & e^{i(\theta_1-\theta_2)} & 0 \\ -e^{-i(\theta_1-\theta_2)} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \cos(\theta_1 - \theta_2)e_3 + \sin(\theta_1 - \theta_2)e_6 \end{aligned}$$

$$\begin{aligned} \text{Similarly } te_4t^{-1} &= \begin{bmatrix} 0 & 0 & -e^{-i(\theta_3-\theta_1)} \\ 0 & 0 & 0 \\ e^{i(\theta_3-\theta_1)} & 0 & 0 \end{bmatrix} \quad (\text{by inspection-analogy with first calculation!}) \\ &= \cos(\theta_3 - \theta_1)e_4 + \sin(\theta_3 - \theta_1)e_7. \end{aligned}$$

Similarly  $te_5t^{-1} = \cos(\theta_2 - \theta_3)e_5 + \sin(\theta_2 - \theta_3)e_8$ .

$$\begin{aligned} \text{Also } te_6t^{-1} &= \begin{bmatrix} e^{i\theta_1} & 0 & 0 \\ 0 & e^{i\theta_2} & 0 \\ 0 & 0 & e^{i\theta_3} \end{bmatrix} \begin{bmatrix} 0 & i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} e^{-i\theta_1} & 0 & 0 \\ 0 & e^{-i\theta_2} & 0 \\ 0 & 0 & e^{-i\theta_3} \end{bmatrix} \\ &= \cos(\theta_1 - \theta_2)e_6 - \sin(\theta_1 - \theta_2)e_3 \\ te_7t^{-1} &= \cos(\theta_3 - \theta_1)e_7 - \sin(\theta_3 - \theta_1)e_4 \\ te_8t^{-1} &= \cos(\theta_2 - \theta_3)e_8 - \sin(\theta_2 - \theta_3)e_5. \end{aligned}$$

Thus the roots are  $\theta_1 - \theta_2$ ,  $\theta_3 - \theta_1 \equiv -2\theta_1 - \theta_2$ ,  $\theta_2 - \theta_3 \equiv 2\theta_2 + \theta_1$ .

There are only two independent roots; these may be taken to be  $\phi_1 \equiv \theta_1 - \theta_2$  and  $\phi_2 \equiv \theta_1 + 2\theta_2$  (so that  $(2\theta_1 + \theta_2) = \phi_1 + \phi_2$ ).