

### Question 8

(i) [4 marks]

The curve  $t \mapsto \exp tX$  is the integral curve of the left-invariant vector field  $X$  through  $e$ , so its tangent vector there (at  $t = 0$ ) is  $X_e$ . Now  $I_*X_e$  is the tangent vector at  $t = 0$  to the curve  $t \mapsto I(\exp tX)$ . Note that  $I(e) = e$ , so  $I_*X_e$  is also a tangent vector at  $e$ . But

$$I(\exp tX) = (\exp tX)^{-1} = \exp(-tX),$$

and the tangent vector to the curve  $t \mapsto \exp(-tX)$  at  $t = 0$  is  $-X_e$ . Thus

$$I_*X_e = -X_e.$$

This is equivalent to the given result when  $G$  is identified with  $T_eG$ .

(ii) [6 marks]

Left translation by  $g \in G$  is the map  $L_g: G \rightarrow G$  given by  $L_g h = gh$ . A  $p$ -form  $\omega$  on  $G$  is left-invariant if, for every  $g \in G$ ,

$$L_g^* \omega = \omega.$$

This means that

$$L_g^*(\omega_g) = \omega_e,$$

since  $L_g e = g$  and  $L_g^*$  maps contragrediently; thus

$$\omega_g = L_{g^{-1}}^* \omega_e.$$

Thus a left-invariant form  $\omega$  is determined completely by its value at  $e$ . Now sums and constant multiples of left-invariant  $p$ -forms are also left-invariant  $p$ -forms; the set of left-invariant  $p$ -forms therefore constitutes a vector space. It follows from the comments above that evaluation at  $e$  is an isomorphism of the space of left-invariant  $p$ -forms with the  $p$ -fold exterior product of  $T_e^*G$ , which is finite-dimensional; thus the set of left-invariant  $p$ -forms is a finite-dimensional vector space.

(iii) [6 marks]

Note that

$$I(R_g h) = (hg)^{-1} = g^{-1}h^{-1} = L_{g^{-1}}I(h),$$

so

$$I \circ R_g = L_{g^{-1}} \circ I.$$

If  $\omega$  is left-invariant then for every  $g \in G$

$$\begin{aligned} R_g^* I^* \omega &= (I \circ R_g)^* \omega \\ &= (L_{g^{-1}} \circ I)^* \omega = I^* L_{g^{-1}}^* \omega \\ &= I^* \omega, \end{aligned}$$

so  $I^* \omega$  is right-invariant. If  $\omega$  is a left-invariant  $p$ -form and  $X_1, X_2, \dots, X_p$  are any  $p$  vectors at  $e$  then

$$\begin{aligned} (I^* \omega)_e(X_1, X_2, \dots, X_p) &= \omega_e(I_* X_1, I_* X_2, \dots, I_* X_p) \\ &= \omega_e(-X_1, -X_2, \dots, -X_p) \\ &= (-1)^p \omega_e(X_1, X_2, \dots, X_p) \end{aligned}$$