

(1)

M2AA2 - MULTIVARIABLE CALCULUS
SOLUTIONS - PROBLEM SHEET 6
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(1) $I = \int_S \frac{\underline{x} \cdot \underline{n}}{|\underline{x}|^3} dS$

If $\underline{F} = \frac{\underline{x}}{|\underline{x}|^3} = \frac{(x, y, z)}{(x^2 + y^2 + z^2)^{3/2}}$ $\Rightarrow \nabla \cdot \underline{F} = 0$ if $\underline{x} \neq 0$

On the sphere $|\underline{x}| = R$, $\underline{n} = \frac{(x, y, z)}{R}$

$$\Rightarrow I = \int_{\text{sphere}} \frac{(x^2 + y^2 + z^2)}{R^4} dS = \frac{1}{R^2} \int_{\text{sphere}} dS = \frac{4\pi R^2}{R^2} = 4\pi$$

If S does not bound the origin, then

$$\int_S \frac{\underline{x} \cdot \underline{n}}{|\underline{x}|^3} dS = \int_V \nabla \cdot \left(\frac{\underline{x}}{|\underline{x}|^3} \right) dV = 0.$$

Using these facts, we see that if $\underline{E} = \frac{1}{4\pi \epsilon_0} \frac{\underline{x} - \underline{a}}{|\underline{x} - \underline{a}|^3}$

we immediately obtain the desired result by shifting the origin to $\underline{x} = \underline{a}$.

(2) $\underline{F}(\underline{x}) = r^{-1} \underline{e}_r$

$$\operatorname{curl} \underline{F} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \underline{e}_1 & h_2 \underline{e}_2 & h_3 \underline{e}_3 \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q_3} \\ h_1 F_1 & h_2 F_2 & h_3 F_3 \end{vmatrix} = \frac{1}{r} \begin{vmatrix} \underline{e}_r & r \underline{e}_\theta & \underline{e}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & 1 & 0 \end{vmatrix} = 0$$

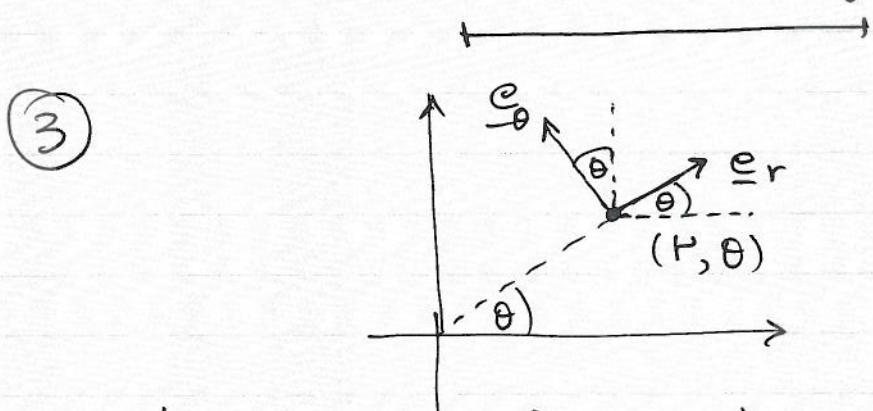
$$\oint \underline{F} \cdot d\underline{s} = \oint \underline{e}_\theta \cdot d\underline{s} \quad \text{since we are on } r=1$$

$$d\underline{s} = (dx, dy) = (d(\cos\theta), d(\sin\theta)) = (-\sin\theta, \cos\theta)d\theta = \underline{e}_\theta d\theta$$

$\Rightarrow \oint \underline{F} \cdot d\underline{s} = \oint d\theta = 2\pi$, but Stokes's theorem which is

$$\iint_S \nabla \times \underline{F} dS = \oint_C \underline{F} \cdot d\underline{s} \text{ does not hold.}$$

The reason is that ~~\underline{F}~~ \underline{F} is not continuous in the region under consideration; \underline{F} is singular at $r=0$.



In terms of i and j we have

$$\underline{e}_r = \cos\theta \underline{i} + \sin\theta \underline{j}, \quad \underline{e}_\theta = -\sin\theta \underline{i} + \cos\theta \underline{j}$$

$$\frac{\partial \underline{e}_r}{\partial \theta} = -\sin\theta \underline{i} + \cos\theta \underline{j} = \underline{e}_\theta$$

$$\frac{\partial \underline{e}_r}{\partial r} = \frac{\partial \underline{e}_\theta}{\partial r} = 0.$$

$$\frac{\partial \underline{e}_\theta}{\partial \theta} = -\cos\theta \underline{i} - \sin\theta \underline{j} = -\underline{e}_r$$

$$\frac{\partial \underline{e}_\theta}{\partial r} = \frac{\partial \underline{e}_z}{\partial r} = \frac{\partial \underline{e}_z}{\partial \theta} = 0$$

$$\text{Given } \nabla = \underline{e}_r \frac{\partial}{\partial r} + \underline{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} + \underline{e}_z \frac{\partial}{\partial z}$$

$$\nabla \cdot \underline{A} = \underline{e}_r \cdot \frac{\partial}{\partial r} (A_1 \underline{e}_r) + A_2 \underline{e}_\theta + A_3 \underline{e}_z$$

$$+ \underline{e}_\theta \cdot \frac{1}{r} \frac{\partial}{\partial \theta} (A_1 \underline{e}_r + A_2 \underline{e}_\theta + A_3 \underline{e}_z)$$

$$+ \underline{e}_z \cdot \frac{\partial}{\partial z} (A_1 \underline{e}_r + A_2 \underline{e}_\theta + A_3 \underline{e}_z)$$

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$$\begin{aligned}
&= \underline{e}_r \cdot \left(\frac{\partial A_1}{\partial r} \underline{e}_r + \frac{\partial A_2}{\partial r} \underline{e}_\theta + \frac{\partial A_3}{\partial r} \underline{e}_z \right) \\
&\quad + \underline{e}_\theta \frac{1}{r} \left(\frac{\partial A_1}{\partial \theta} \underline{e}_r + A_1 \frac{\partial \underline{e}_r}{\partial \theta} + \frac{\partial A_2}{\partial \theta} \underline{e}_\theta + A_2 \frac{\partial \underline{e}_\theta}{\partial \theta} + \frac{\partial A_3}{\partial \theta} \underline{e}_z \right) \\
&\quad + \underline{e}_z \cdot \left(\frac{\partial A_1}{\partial z} \underline{e}_r + \frac{\partial A_2}{\partial z} \underline{e}_\theta + \frac{\partial A_3}{\partial z} \underline{e}_z \right) \\
&= \underline{e}_r \cdot \left(\frac{\partial A_1}{\partial r} \underline{e}_r \right) + \underline{e}_\theta \frac{1}{r} \cdot \left(A_1 \underline{e}_\theta + \frac{\partial A_2}{\partial \theta} \underline{e}_\theta \right) + \underline{e}_z \cdot \left(\frac{\partial A_3}{\partial z} \underline{e}_z \right) \\
&= \frac{\partial A_1}{\partial r} + \frac{1}{r} A_1 + \frac{1}{r} \frac{\partial A_2}{\partial \theta} + \frac{\partial A_3}{\partial z} \quad \text{which is the familiar formula}
\end{aligned}$$

$$\begin{aligned}
\nabla \times \underline{A} &= \underline{e}_r \times \left[\frac{\partial A_1}{\partial r} \underline{e}_r + \frac{\partial A_2}{\partial r} \underline{e}_\theta + \frac{\partial A_3}{\partial r} \underline{e}_z \right] \\
&\quad + \underline{e}_\theta \frac{1}{r} \times \left[\frac{\partial A_1}{\partial \theta} \underline{e}_r + A_1 \underline{e}_\theta + \frac{\partial A_2}{\partial \theta} \underline{e}_\theta - A_2 \underline{e}_r + \frac{\partial A_3}{\partial \theta} \underline{e}_z \right] \\
&\quad + \underline{e}_z \times \left[\frac{\partial A_1}{\partial z} \underline{e}_r + \frac{\partial A_2}{\partial z} \underline{e}_\theta + \frac{\partial A_3}{\partial z} \underline{e}_z \right] \\
&= \frac{\partial A_2}{\partial r} (\underline{e}_r \times \underline{e}_\theta) + \frac{\partial A_3}{\partial r} (\underline{e}_r \times \underline{e}_z) \\
&\quad + \frac{1}{r} \left(\frac{\partial A_1}{\partial \theta} - A_2 \right) (\underline{e}_\theta \times \underline{e}_r) + \frac{1}{r} \frac{\partial A_3}{\partial \theta} (\underline{e}_\theta \times \underline{e}_z) \\
&\quad + \frac{\partial A_1}{\partial z} (\underline{e}_z \times \underline{e}_r) + \frac{\partial A_2}{\partial z} (\underline{e}_z \times \underline{e}_\theta)
\end{aligned}$$

Now use RHT rule for cross products.

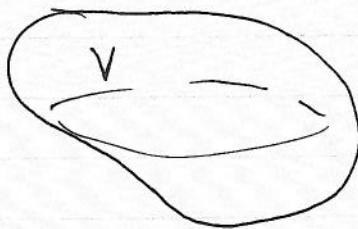
$$\underline{e}_r \times \underline{e}_\theta = \underline{e}_z \quad \underline{e}_r \times \underline{e}_z = -\underline{e}_\theta$$

$$\underline{e}_\theta \times \underline{e}_r = -\underline{e}_z \quad \underline{e}_\theta \times \underline{e}_z = \underline{e}_r$$

$$\nabla \times \underline{A} = \left(\frac{1}{r} \frac{\partial A_3}{\partial \theta} - \frac{\partial A_2}{\partial z} \right) \underline{e}_r + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial r} \right) \underline{e}_\theta + \left(\frac{\partial A_2}{\partial r} + \frac{1}{r} A_2 - \frac{1}{r} \frac{\partial A_1}{\partial \theta} \right) \underline{e}_z$$

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(4)



$$\nabla^2 u = m^2 u \quad x \in \mathbb{R}^3$$

u , or $\frac{\partial u}{\partial n}$ given.

Let u_1, u_2 be two such solutions.

Then $V = u_1 - u_2$ satisfies

$$\nabla^2 V = m^2 V \text{ in } V$$

$$V \text{ or } \frac{\partial V}{\partial n} = 0 \text{ on } S$$

$$\text{Consider } \int_V \nabla \cdot (V \nabla V) dV = \int_V (V \nabla^2 V + |\nabla V|^2) dV = \int_V (m^2 V^2 + |\nabla V|^2) dV \geq 0$$

But using the Divergence Thm, we also have

$$\int_V \nabla \cdot (V \nabla V) dV = \int_S V \frac{\partial V}{\partial n} dS = 0 \quad \text{since } V \text{ or } \frac{\partial V}{\partial n} \text{ are zero on } S.$$

$$\Rightarrow \int_V (m^2 V^2 + |\nabla V|^2) dV = 0 \Rightarrow V \equiv 0 \text{ ie uniqueness}$$



(5)

First part is in your notes, ie

$$\phi(r, \theta) = C_0 \ln r + D_0 + \sum_{n=1}^{\infty} \left[(A_n r^n + B_n r^{-n}) \cos n\theta + (C_n r^n + D_n r^{-n}) \sin n\theta \right]$$

$$\text{To solve } \nabla^2 \phi = 0 \quad n < 0$$

$$\phi(a, \theta) = \sin \theta$$

$$\text{Banded } \phi \Rightarrow \phi(r, \theta) = D_0 + \sum_{n=1}^{\infty} [C_n r^n \sin n\theta + A_n r^n \cos n\theta]$$

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$$\text{At } r=a \quad \sin\theta = D_0 + \sum_{n=1}^{\infty} [C_n a^n \sin n\theta + A_n a^n \cos n\theta]$$

$$\text{Hence } D_0 = A_n = 0, C_1 = \frac{1}{a}, C_2 = C_3 = \dots = 0$$

$$\phi(r, \theta) = \frac{r}{a} \sin\theta$$

$$r > a \quad \phi \rightarrow 0 \quad \text{as} \quad r \rightarrow \infty \quad \Rightarrow$$

$$\phi(r, \theta) = \sum_{n=1}^{\infty} [B_n r^{-n} \cos n\theta + D_n r^{-n} \sin n\theta]$$

$$\text{Again BC at } r=a \text{ gives } B_n = 0 \quad D_1 = a \\ D_2 = D_3 = \dots = 0$$

$$\Rightarrow \phi(r, \theta) = \underbrace{\frac{a}{r} \sin\theta}_{\text{---}}$$

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$$\phi = \phi(r) \quad r = (x^2 + y^2 + z^2)^{1/2} \quad \frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r} \text{ etc}$$

$$\nabla \phi = \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right) = \left(\frac{\partial \phi}{\partial r} \frac{\partial r}{\partial x}, \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial y}, \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial z} \right)$$

$$= \phi'(r) \left(\frac{x}{r}, \frac{y}{r}, \frac{z}{r} \right) = \phi'(r) \frac{x}{r}$$

$$\nabla^2 \phi = \nabla \cdot (\nabla \phi) = \frac{\partial}{\partial x} \left(\phi'(r) \frac{x}{r} \right) + \frac{\partial}{\partial y} \left(\phi'(r) \frac{y}{r} \right) + \frac{\partial}{\partial z} \left(\phi'(r) \frac{z}{r} \right)$$

$$= \frac{\phi'(r)}{r} - \frac{x^2}{r^3} \phi'(r) + \phi''(r) \frac{x}{r} + 6 \text{ similar terms}$$

$$= \phi''(r) + \frac{2}{r} \phi'(r) \quad - \text{see notes also}$$

$$\text{If } \nabla^2 \phi = 1 \quad \text{and} \quad \phi(a) = 1 \quad 0 < r < a$$

Since BC is independent of θ , $\phi = \phi(r) \Rightarrow$

(6)

$$\phi'' + \frac{2}{r}\phi' = 1 \Rightarrow \frac{1}{r^2} \frac{d}{dr}(r^2\phi') = 1$$

$$r^2\phi' = \frac{r^3}{3} + A \rightarrow \phi = \frac{r^2}{6} - \frac{A}{r} + B$$

$A=0$ for finite solutions at $r=0$, $\phi(0)=1 \Rightarrow \frac{a^2}{6} + B = 1$

$$\phi(r) = \frac{1}{6}(r^2 - a^2) + 1$$

↔

$$\nabla^2\phi = f \quad \text{in } V$$

$$g \frac{\partial \phi}{\partial n} + \phi = 0 \quad \text{on } S \quad g(x) \geq 0 \text{ on } S.$$

Suppose there exist two solutions ϕ_1, ϕ_2 and consider the problem for the difference $\Phi = \phi_1 - \phi_2$ we have

$$\nabla^2\Phi = 0 \quad \text{in } V$$

$$g \frac{\partial \Phi}{\partial n} + \Phi = 0 \quad \text{on } S. \quad (*)$$

$$\text{Now } \int_V \nabla(\Phi \nabla \Phi) dV = \int_V [\Phi \nabla^2 \Phi + |\nabla \Phi|^2] dV = \int_V |\nabla \Phi|^2 dV$$

$$\text{Also } \int_V \nabla(\Phi \nabla \Phi) dV = \int_S \Phi \frac{\partial \Phi}{\partial n} dS = \int_S -g(x) \left(\frac{\partial \Phi}{\partial n} \right)^2 dS$$

using (*)

Hence

$$\int_V |\nabla \Phi|^2 dV = \int_S -g(x) \left(\frac{\partial \Phi}{\partial n} \right)^2 dS \leq 0 \text{ by hypothesis}$$

Can only be satisfied if $\Phi = \text{const.}$

But the const. $= 0$ on $S \Rightarrow \Phi = 0 \Rightarrow \underline{\phi_1 = \phi_2}$

If $g(x) < 0$ theorem cannot be proven as above.

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$$\phi = x \quad - \text{ clearly } \nabla^2 \phi = 0$$

In spherical polars, $\frac{\partial \phi}{\partial n} = \nabla \phi \cdot \underline{n} = \underline{i} \cdot (\sin \theta \cos \phi, \dots, \dots) = \sin \theta \cos \phi = x$

\Rightarrow If $g = -1$ we have a solution.
satisfying $g \frac{\partial \phi}{\partial n} + \phi = 0$

(8)

$$\int_V |\nabla(w-u)|^2 dV = \int_V (\nabla w - \nabla u) \cdot (\nabla w - \nabla u) dV$$

$$= \int_V (|\nabla w|^2 - 2 \nabla w \cdot \nabla u + |\nabla u|^2) dV = \int_V |\nabla w|^2 dV + \int_V |\nabla u|^2 dV - \int_V 2(\nabla w \cdot \nabla u) dV$$

Therefore

$$\int_V |\nabla(w-u)|^2 dV + 2 \int_V \nabla u \cdot (\nabla(w-u)) dV$$

$$= \int_V |\nabla w|^2 dV - \int_V |\nabla u|^2 dV \quad \text{as required.}$$

We need to prove that the LHS ≥ 0 . Clearly 1st term is

for

$$\int_V \nabla u \cdot \nabla(w-u) dV \quad \text{consider} \int_V \nabla \cdot [(w-u) \nabla u] dV$$

$$\Rightarrow \int_V \nabla \cdot [(w-u) \nabla u] dV = \int_V (w-u) \nabla^2 u dV + \int_V \nabla(w-u) \cdot \nabla u dV$$

↓

Divergence thm. $\rightarrow \int_S (w-u) \frac{\partial u}{\partial n} dS = 0$ since $u=w$ on S

Also $\nabla^2 u = 0$ in $V \Rightarrow \int_V \nabla u \cdot \nabla(w-u) dV = 0$

This completes the proof.

(9) for harmonic functions ϕ, ψ , $\nabla^2\phi=0$, $\nabla^2\psi=0$
we have $\nabla \cdot (\psi \nabla \phi) - \nabla \cdot (\phi \nabla \psi) = 0$; by the divergence theorem we get

$$0 = \int_V \nabla \cdot (\psi \nabla \phi - \phi \nabla \psi) dV = \int_S \left(\psi \frac{\partial \phi}{\partial n} - \phi \frac{\partial \psi}{\partial n} \right) dS$$

Now $\psi = \frac{1}{r}$ is harmonic if $r \neq 0 \Rightarrow$ result follows.

If V is the volume $\varepsilon \leq r \leq a$, we have two surfaces $S_1 : r=a$, $S_\varepsilon : r=\varepsilon$. We have

$$\int_{S_1 + S_\varepsilon} \left(\phi \nabla \left(\frac{1}{r} \right) - \frac{1}{r} \nabla \phi \right) \cdot \underline{n} dS = 0 \Rightarrow$$

$$\text{On } S_1: \int_{S_1} \left(\phi \left(-\frac{1}{r^2} \hat{r} \right) - \frac{1}{r} \nabla \phi \right) \cdot \hat{r} dS' = -\frac{1}{a^2} \int_{S_1} \phi dS - \frac{1}{a} \int_{S_1} \nabla \phi \cdot \underline{n} dS$$

$$\text{Now } \phi \text{ is harmonic} \Rightarrow \int_V \nabla \cdot (\nabla \phi) dV = \int_V \nabla^2 \phi dV = 0$$

$$\text{and } \int_V \nabla \cdot (\nabla \phi) dV = \int_{S_1} \nabla \phi \cdot \underline{n} dS = 0.$$

$$\text{So } \int_{S_1} \left[\phi \left(\frac{1}{r} \right) - \frac{1}{r} \nabla \phi \right] \cdot \underline{n} dS = -\frac{1}{a^2} \int_{S_1} \phi dS \quad (*)$$

Now consider S_ε . Here $\underline{n} = -\hat{r}$

$$\int_{S_\varepsilon} (1) = \int_{r=\varepsilon} \phi \left(-\frac{1}{\varepsilon^2} \hat{r} \right) \hat{r} \cdot (-\hat{r}) dS + \int_{r=\varepsilon} \left(+\frac{1}{\varepsilon} \nabla \phi \right) \cdot \hat{r} dS$$

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$\int_{S_\epsilon} \rightarrow \phi(0) 4\pi + O(\epsilon)$. Put this together with (*) to give $\phi(0) = \frac{1}{4\pi a^2} \int_{S_1} \phi dS$ as required.

To prove the maximum principle using this.

Suppose ϕ attains a maximum at an interior point. Let this value be M and move the origin so that the point where the max is attained is the origin.

Then

$$\phi(0) = \frac{1}{4\pi a^2} \int_{S_1} \phi dS, \text{ so for a small } a \text{ enough we have}$$

$$\phi(0) = M = \frac{1}{4\pi a^2} \int_{S_1} \phi dS \leq \frac{1}{4\pi a^2} \int_{S_1} M dS = M$$

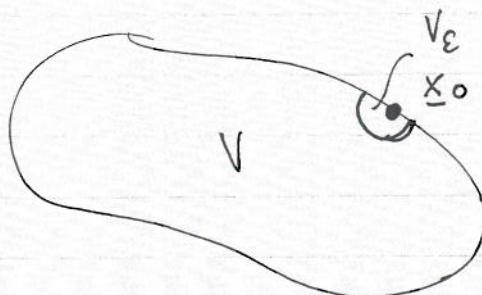
i.e. $M \leq M$ for any sphere radius a which is contained in V .

$\Rightarrow \phi = M$ for every sphere around the origin
 $\Rightarrow \phi$ is a constant. Assumption of a local maximum invalid. \Rightarrow maximum has to be on the boundary.
 For a minimum $\phi \rightarrow -\phi$ and repeat argument.



(10) First part is in your notes. Identify $G(\underline{x}; \underline{x}_0) = -\frac{1}{4\pi} \frac{1}{|\underline{x}-\underline{x}_0|}$

If \underline{x}_0 is on the boundary of S



puncture a semi-circular sphere out.

Basic formula comes from

$$\iiint_{V-V_\varepsilon} (\phi \nabla^2 G - G \nabla^2 \phi) dV = \iint_{S+S_\varepsilon} \left(\phi \frac{\partial G}{\partial n} - G \frac{\partial \phi}{\partial n} \right) dS$$

where $\nabla^2 \phi = f(x)$ in V

$$\nabla^2 G = 0 \text{ in } V - V_\varepsilon$$

$$\text{The LHS} \rightarrow \int_V -Gf dV = \frac{1}{4\pi} \int_V \frac{f(x)}{|x-x_0|} dV$$

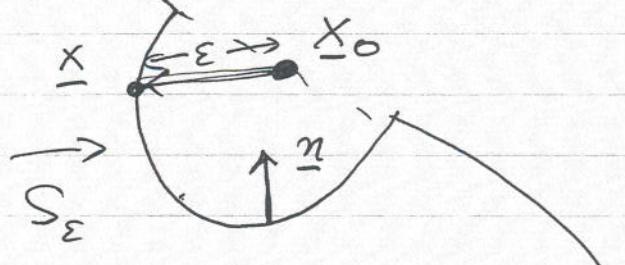
$$\begin{aligned} \text{RHS} &\rightarrow \int_S \left[\phi \frac{\partial}{\partial n} \left(-\frac{1}{4\pi|x-x_0|} \right) + \frac{1}{4\pi|x-x_0|} \frac{\partial \phi}{\partial n} \right] dS \\ &= \frac{1}{4\pi} \int_S \left(\frac{1}{|x-x_0|} \frac{\partial \phi(x)}{\partial n} - \phi(x) \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) \right) dS \end{aligned}$$

So all the details are in $I_\varepsilon = \int_{S_\varepsilon} (\dots)$

$$I_\varepsilon = \frac{1}{4\pi} \iint_{S_\varepsilon} \left(\frac{1}{|x-x_0|} \frac{\partial \phi}{\partial n} - \phi(x) \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) \right) dS$$

Introduce a spherical polar coordinate system with origin at $x = x_0$.

$$S_\varepsilon : |x-x_0| = \varepsilon$$



$$\begin{aligned}
 I_\varepsilon &\approx \frac{1}{4\pi} \int_{S_\varepsilon} \left[f \frac{1}{\varepsilon} \frac{\partial \phi}{\partial n}(\underline{x}_0) - \phi(\underline{x}_0) \left(-\frac{\partial}{\partial n} \left(\frac{1}{r} \right) \right)_{r=\varepsilon} \right] dS \\
 &\approx \frac{1}{4\pi} \int_{S_\varepsilon} \left[\frac{1}{\varepsilon} \frac{\partial \phi}{\partial n}(\underline{x}_0) - \frac{\phi(\underline{x}_0)}{\varepsilon^2} \right] dS \\
 \rightarrow & - \frac{\phi(\underline{x}_0)}{\frac{4\pi}{4\pi\varepsilon^2}} \int_{S_\varepsilon} dS = - \frac{\phi(\underline{x}_0)}{\frac{4\pi}{4\pi\varepsilon^2}} \cdot 2\pi\varepsilon^2 \\
 &= -\frac{1}{2} \phi(\underline{x}_0)
 \end{aligned}$$

Note The $\int_{S_\varepsilon} dS = 2\pi\varepsilon^2$ because it's half a sphere.

Put together to find

$$4\pi \left(\frac{1}{2} \phi(\underline{x}_0) \right) = - \int_V \frac{f(x)}{|x-\underline{x}_0|} dV + \int_S \left[\frac{1}{|x-\underline{x}_0|} \frac{\partial \phi}{\partial n}(x) - \phi(x) \frac{\partial}{\partial n} \left(\frac{1}{|x-\underline{x}_0|} \right) \right] dS$$

If \underline{x}_0 is inside V , ie not on the boundary
then the LHS is with $\frac{1}{2} \phi(\underline{x}_0)$ not $\frac{1}{2}$.