DEPARTMENT	OF ELECTRICA	L AND ELECTRO	ONIC ENGINEERING
EXAMINATIONS	S 2006		

MSc and EEE PART IV: MEng and ACGI

CURRENT-MODE ANALOGUE SIGNAL PROCESSING

Wednesday, 26 April 10:00 am

Time allowed: 3:00 hours

There are SIX questions on this paper.

Answer FOUR questions.

All questions carry equal marks

Any special instructions for invigilators and information for candidates are on page 1.

Examiners responsible

First Marker(s):

E. Drakakis

Second Marker(s): E. Rodriguez-Villegas

Special instructions for students

$$\sinh(x) = \frac{\exp(x) - \exp(-x)}{2}$$

$$\cosh(x) = \frac{\exp(x) + \exp(-x)}{2}$$

$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)}$$

$$\operatorname{sech}(x) = \frac{1}{\cosh(x)}$$

$$\operatorname{sech}^{2}(x) + \tanh^{2}(x) = 1$$

The transfer function of an Infinite Impulse Response (IIR) filter of order N is given by:

$$y(m) = \sum_{n=1}^{N} a(n)y(m-n) + \sum_{n=0}^{N} b(n)x(m-n)$$

In this question the design of an IIR filter of order 2 will be outlined using switched current cells. This is a low-pass filter with a break frequency $f_B = 0.35 f_S$ (f_S is the switching frequency). The filter nominal pass-band gain is unity. The filter coefficients are:

j	a(j)	b(j)
)		0.44
1	0.76	0.88
2	0.45	0.44

- Draw a block diagram of such a filter, in terms of unity delay elements, gain (a) elements and summing junctions.
- Design a switched current "branching element" cell which for a given input generates two outputs each equal to half the input. Discuss the effect of [5] transistor mismatch.

(c)

- Use the divide-by-two branching element from part (b) to design one of the filter i) coefficients of part (a) to a coefficient absolute tolerance of 5-10⁻³. Draw your circuit diagram in terms of branching cells, NOT in terms of transistors. (hint: you will need to construct a binary representation of the filter coefficient by multiplying it by a suitable power of 2, and use several branching stages).
- Estimate the number of control clock phases required for each coefficient. ii)
- Estimate the number of transistors, including switches and bias current sources required to implement the filter using this technique.
- Estimate the number of phases needed to run this filter. If the transistors have a iv) transit frequency of 10 GHz, what is the maximum signal frequency the filter can handle? Explain your answer.

[12]

[3]

In this question "x" denotes the current input terminal of a current conveyor, and "y" denotes the other input terminal.

- (a) Describe the function of an ideal 3rd generation current conveyor, and write an equation relating the voltages and currents at its terminals. What is the application of the CCIII? [5]
- (b) i) What is the terminal impedance of an ideal CCIII on the "x" terminal if the "y" terminal is grounded?
 - ii) What is the terminal impedance of a CCIII on the "y" terminal if the "y" terminal is grounded?
 - iii) Without drawing a circuit diagram describethe kind of feedback connections and the magnitude of the loop gain of each required to approximately obtain the terminal characteristics of an ideal CCIII using real devices. Discuss the consequences of such a circuit topology. [5]
- (c) Draw the circuit diagram of a current difference amplifier of gain +10 using only CCII-current conveyors. [5]
- (d) Use your result from Question 2(c) above, together with any other current conveyors needed to design a differential-to-single-ended current mode 2nd order active high pass filter following the Sallen-Key methodology. [5]

In this question CFOA means Current feedback op-amp

- (a)
 i) Write a matrix equation describing the output of an ideal CFOA in terms of its inputs.
 - ii) Write an equation for the transfer function of a CFOA with a finite transimpedance, but otherwise ideal.
 - iii) Draw a circuit diagram for a non-inverting voltage amplifier constructed around an finite gain but otherwise ideal CFOA.
 - iv) Write an expression for the gain of this amplifier in terms of the CFOA gain and any resistors used. What is the limit of this expression as the transimpedance goes to infinity? [5]
- (b)
 i) Write an equation describing the frequency dependent transfer function of a realistic CFOA in terms of its inputs. Include the effect of a finite, frequency dependent transimpedance only.
 - ii) What is the low frequency gain of this model? What is the bandwidth? What is the gain-bandwidth product? [7]
- i) Extend the model of part (b) to include a finite input impedance at the inverting input. Assign a single pole model, at a time constant τ₁, to this input impedance.
 - ii) Show that the resulting non-inverting amplifier is a band-pass filter. Calculate the centre frequency and quality factor of this filter. Assume the low frequency transimpedance is much larger than any other impedance in the problem.
 - iii) Comment on your result. How does the filter Q scale with the ratio of the input pole frequency (typically GHz) to the transimpedance pole frequency (typically kHz)?

[8]

(a) Derive the bipolar translinear principle with reference to a loop containing 2m base-emitter junctions. State all the assumptions that you make and list the conditions which must be satisfied in order for this principle to be valid.

[3]

(b) Compare the translinear principle relations for the MOS and the Bipolar cases

[2]

[3]

- (c) Figure 4.1 illustrates a translinear circuit whose differential current output realises a trigonometric approximation.
 - (i) Express the currents I_3 and I_4 in terms of I and I_x .
 - (ii) Next, express the differential output $I_2 I_1$ in terms of I and I_x and show that when $I_x = yI$ holds: $I_2 I_1 = \frac{2}{3} \frac{(2y y^3)}{I + y^2} I$. You may assume that the transistors' beta value is large. [4]

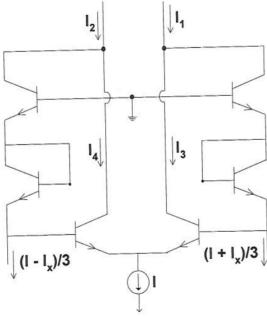


Figure 4.1

- (d) Figure 4.2 illustrates a translinear circuit whose output current I_z can implement a variety of trigonometric approximations.
 - (i) Express the current $\,I_2\,$ in terms of $\,I,I_x\,$ and the output current $\,I_z\,$.

[2]

- (ii) Next, express the output current I_z in terms of I, I_x and the emitter area A. [3]
- (iii) Determine the emitter area A so that

$$I_z = 1.05 I + 3.45 I_X + 0.7 \left[\frac{{I_X}^2}{I} - \frac{{I_X}^3}{I^2} \right].$$
 [3]

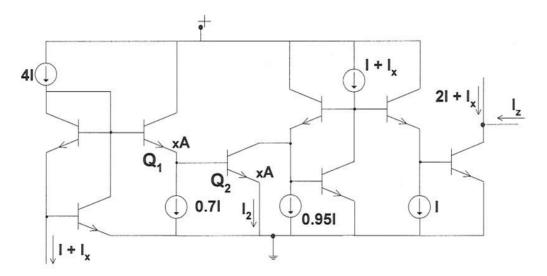


Figure 4.2

(a) Figure 5.1 illustrates a general companding circuit.

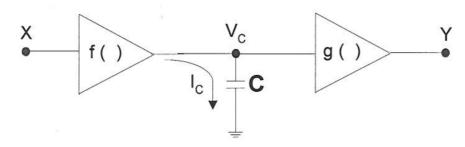


Figure 5.1

- (i) Derive the condition under which the circuit operates as an input-output linear integrator.
- (ii) If the input signal X is a current of value I_{in} and the output signal Y is a current $g(V_C) = I_T \tanh(\alpha V_C)$ with $\alpha = V_T^{-1}$ and I_T a constant with dimensions of current, determine the function f() which ensures that the circuit operates as an input-output linear companding integrator.

[2]

[2]

(b) You are given the following state-space:

$$x_{1}(t) = -\omega_{0} x_{1}(t) + \omega_{0} x_{2}(t)$$

$$x_{2}(t) = -2\omega_{0} x_{1}(t) + \omega_{0} x_{2}(t) + \omega_{0} U(t)$$

$$y(t) = x_{1}(t)$$

where U(t) denotes the input, y(t) denotes the output, $x_1(t)$ and $x_2(t)$ are state variables and a dot above a variable denotes time-differentiation. The input U is tuned appropriately to initially start oscillation.

(i) Show that the transfer function of the above oscillator is provided by the relation: $H(s) = \frac{\omega_0^2}{s^2 + \omega_0^2}$ [3]

- (ii) Using the exponential mappings $x_j = I_0 \exp\left(\frac{V_j}{V_T}\right)$ (j = 1,2) and $U = I_S \exp\left(\frac{V_U}{V_T}\right)$ show that the above linear state-space equations can be transformed into non-linear log-domain design equations (I_S denotes the reverse saturation current of a bipolar junction transistor). [6]
- (iii) Sketch the transistor level implementation of the log-domain oscillator which realises these design relations and choose DC bias current values to give an oscillation frequency $\omega_0 = 2\pi (5 \times 10^6)$ rad/s. You may assume that all capacitors to be used are of value 7.5 pF. [7]

- Derive and sketch the adjoint network of a resistor, a nullor and a voltage amplifier
- [6]

- (b)
- Figure 6.1 illustrates a typical current amplifier. Show that (i)

$$\frac{i_{out}}{i_{in}} = \frac{A_i \left(I + \frac{R_2}{R_I} \right)}{A_i + \left(I + \frac{R_2}{R_I} \right)} \text{ with } A_i \text{ denoting the gain of the amplifier.}$$

[3]

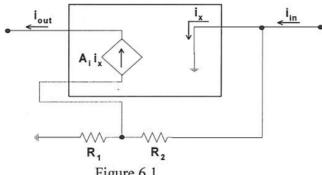


Figure 6.1

Figure 6.2 illustrates a current-mode Sallen-Key filter. Based on the

results you derived in (i) show that its transfer function is provided by the relation
$$\frac{I_{out}(s)}{I_{in}(s)} = \frac{G}{(RC)^2 s^2 + (3-G)(RC)s + 1}$$
 where $G = I + \frac{R_2}{R_1}$ and $A_i >> 1$.

[5]

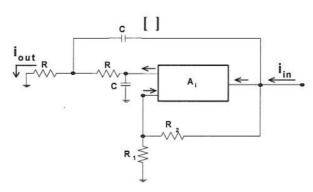
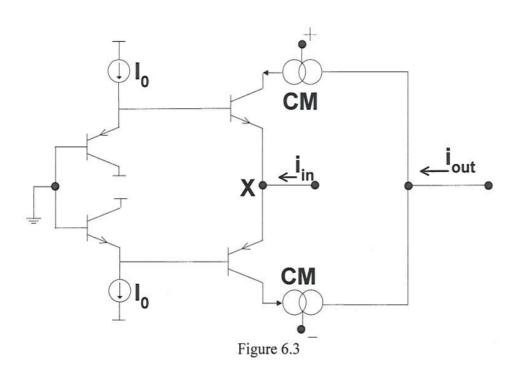


Figure 6.2

- (c) Figure 6.3 shows the architecture of a simple current-follower, where the Symbols CM represent current-mirrors with an arrow marking their input side.
 - (i) Derive expressions for d.c. input offset voltage and small-signal input resistance at node X. [2]

Explain with the aid of a diagram in each case, how the circuit can be modified to:

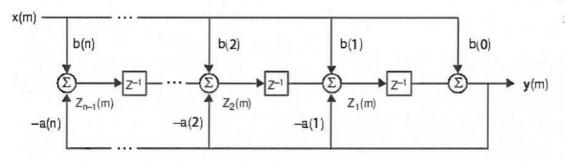
- (ii) Reduce the d.c. offset without increasing the small-signal input resistance
- (iii) Reduce the small signal input resistance without increasing the value of I_0 . [2]



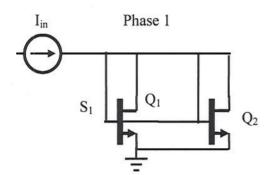
Current-Mode Analogue Signal Processing E4.16
Answers-Q1-Q3-6pages. 2006

ANSWER Q1:

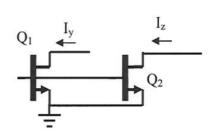
a) [bookwork]



b) [computed example]



Phase 2



Transistor mismatch has the effect that $I_y = \frac{I}{2}(1+\varepsilon)$, $I_z = \frac{I}{2}(1-\varepsilon)$

[2]

[3]

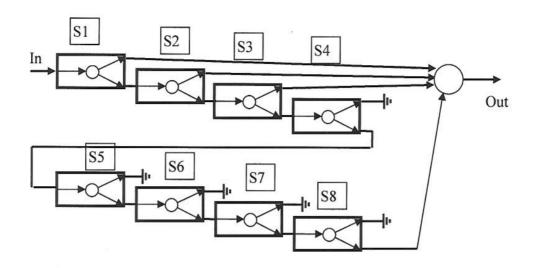
[3]

c) [computed example]

A binary representation of a coefficient can be implemented by the branching elements. Each stage needs a separate phase, so an N-bit representation needs N phases: For example, 0.88 = 0.11100001 in the required 8 bit accuracy.

[2]

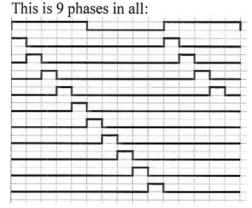
A block diagram of a circuit which can do this is:



[4]

Similar circuits are needed for each of the other 4 coefficients.

The coefficient itself needs 8 phases (1 for each bit, plus an extra one for the signal duplication so that 1 copy is fed to the coefficient and 1 to the delay element.



[2]

To estimate the number of transistors, each duplicator is 2 memory + 6 switches + 2 current bias sources = 10 FET x8 = 80

Each delay-duplicator has to be a CCI so it is another 3 memories +6 switches +3 current sources =12 FET x 6=72

So the total circuit has about 152 transistors and 9 phases.

[2]

The transistors need to settle to 0.005 so each subphase (9+1=10 in a period) needs to be such that

$$e^{-2\pi f_T T} \ge 0.995 \Rightarrow T \ge \frac{1}{400\pi f_T}$$
. For $f_T = 10 GHz \Rightarrow T \ge 126 ns$. The sampling frequency

needs to be 10 times lower than the switch phase frequency, i.e. $f_s \le \frac{1}{1.26 \mu s} = 796 kHz$ and the Nyquist frequency is again half this so $f_N = 388 kHz$

[2]

Note: Partial of full credit will be awarded for any reasonable answer to these estimates.

Current Mode ASP - ANSWERS page 2 of 6

ANSWERS Q2:

a) [bookwork]

$$\begin{bmatrix} i_{y} \\ v_{x} \\ i_{z} \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} v_{y} \\ i_{x} \\ v_{z} \end{bmatrix}$$

$$V_{R}$$

This is an ideal current meter. The two inputs together behave like an ideal node

[5]

b) [interpretation of theory]

From the behavioural equation, if y is grounded, $v_x = 0 \Rightarrow Z_x = 0$.

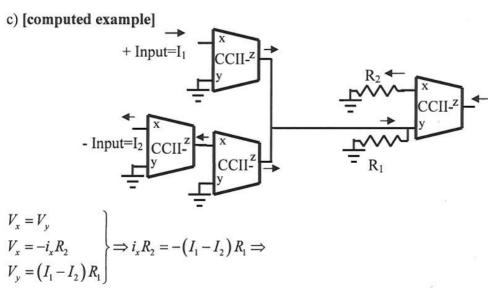
Similarly, if x is grounded, $v_v = 0 \Rightarrow Z_v = 0$.

To obtain zero terminal impedance on the terminals we need unity gain positive feedback connected in series with each of the inputs. Since the output is required to be a current source the connection at the output side is a shunt connection. So a series-shunt positive feedback connection at each of the inputs is required. The opposite current polarity requires an extra inversion in one of the feedback connections.

Such a circuit is likely to be unstable in a real implementation. Alternatively, a very large loop gain shunt-series connection is required, severely restricting the bandwidth of the device.

(Note: Either answer will be accepted as correct)

[5]

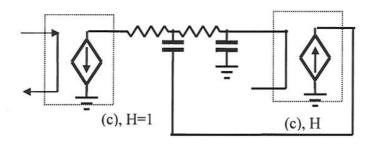


$$V_y = (I_1 - I_2) R_1$$

 $i_z = -i_x = \frac{R_1}{R_2} (I_1 - I_2) \Rightarrow R_1 = 10 R_2$

[5]

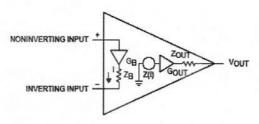
d) [computed example]



[5]

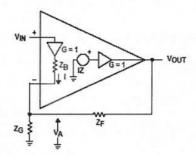
ANSWER Q3.

a) [bookwork+extensions]



 $v_{out} = Z_T I_{IN}$, for an ideal CFOA $Z_T = \infty$.

The non-inverting amplifier diagram is the same as with a voltage op-amp:



 $V_{out} = Z_T I$ and the gain goes to infinity as $Z_T \to \infty$, with the input current out of the inverting input. The inverting input voltage follows that of the non-inverting input.

Since:

$$\begin{split} &V_{-}=V_{+}\\ &i_{-}+\frac{V_{-}}{R_{G}}+\frac{\left(V_{-}-V_{out}\right)}{R_{F}}=0\\ &\Rightarrow G=\frac{V_{out}}{V_{+}}=Z_{T}\left(\frac{1}{R_{G}}+\frac{1}{R_{F}}\right)\bigg/\bigg(1+\frac{Z_{T}}{R_{F}}\bigg)\\ &V_{out}=-Z_{T}i_{-}\\ &\lim_{Z\to\infty}G=1+\frac{R_{F}}{R_{G}}\equiv G_{0} \end{split}$$

b) Let
$$Z_T = \frac{Z_0}{1 + s\tau}$$
. Then,

$$G = \frac{V_{out}}{V_{+}} = \frac{Z_{0}}{1 + s\tau} \left(\frac{1}{R_{G}} + \frac{1}{R_{F}} \right) / \left(1 + \frac{Z_{0}}{R_{F} (1 + s\tau)} \right) = \frac{Z_{0}}{R_{F} + Z_{0}} G_{0} \left(\frac{1}{1 + \frac{R_{F}}{R_{F} + Z_{0}} s\tau} \right)$$

The low frequency gain is clearly:

$$G(0) = \frac{G_0}{R_E / Z_0 + 1}$$

the bandwidth: $\omega_0 = \frac{1}{\tau} \left(1 + \frac{Z_0}{R_F} \right) \simeq \frac{Z_0}{\tau R_F}$ depends only on R_F , an the gain bandwidth

product is:

Current Mode ASP - ANSWERS

[5]

$$\omega_0 G(0) = \frac{G_0}{R_F/Z_0 + 1} \simeq \frac{Z_0}{\tau R_F} \left(1 + \frac{R_F}{R_G} \right)$$
, which is clearly not a constant.

[7]

c) we allow for a finite $R_{in} = R_0 / (1 + s\tau_1)$:

$$\begin{split} &V_{-} = V_{+} + i_{-}R_{in} \\ &i_{-} + \frac{V_{-}}{R_{G}} + \frac{(V_{-} - V_{out})}{R_{F}} = 0 \\ &\Rightarrow G = \frac{V_{out}}{V_{+}} = Z_{T} \left(\frac{1}{R_{G}} + \frac{1}{R_{F}} \right) / \left(1 + \frac{R_{in}}{R_{G}} + \frac{R_{in}}{R_{F}} + \frac{Z_{T}}{R_{F}} \right) \\ &V_{out} = -Zi_{-} \\ &\Rightarrow G = \frac{Z_{T}G_{0}}{R_{F}} / \left(1 + \frac{R_{m}G_{0}}{R_{F}} + \frac{Z_{T}}{R_{F}} \right) = \frac{Z_{T}G_{0}}{R_{F}} + \frac{Z_{0}}{G_{0}} \frac{G_{0}}{(1 + s\tau)} \\ &= \frac{Z_{0}G_{0}}{R_{F}} \left(1 + s\tau_{1} \right) (1 + s\tau) + R_{0}G_{0} \left(1 + s\tau \right) + Z_{0} \left(1 + s\tau_{1} \right) = \\ &= \frac{Z_{0}G_{0}}{R_{F}} \frac{1 + s\tau_{1}}{R_{F}} + \frac{Z_{0}}{R_{0}R_{0}} \frac{1 + s\tau_{1}}{1 + \left(\frac{R_{F}(\tau + \tau_{1}) + G_{0}R_{0}\tau + Z_{0}\tau_{1}}{R_{F} + Z_{0} + G_{0}R_{0}} \right) s + s^{2} \frac{R_{F}\tau\tau_{1}}{R_{F} + Z_{0} + G_{0}R_{0}} = \\ &LPF + BPF \text{, both 2nd order.} \end{split}$$

with
$$G_0 = 1 + \frac{R_F}{R_G}$$

two filter transfer functions share natural frequency and Q:

$$\omega_0 = \sqrt{\frac{1 + Z_0/R_F + G_0R_0/R_F}{\tau\tau_1}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F + G_0R_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_F \left(\tau + \tau_1\right) + G_0R_0\tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_F}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_0}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_0}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau + Z_0\tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_0}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0/R_0}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau_1} \sqrt{\frac{\tau\tau_1}{1 + Z_0}} \; , \; Q = \frac{R_F + Z_0 + G_0R_0}{R_0 \tau_1} \sqrt{\frac{\tau$$

if Z_0 is by far the largest term, as is usually the case,

$$\omega_0 = \sqrt{\frac{1 + Z_0/R_F + G_0R_0/R_F}{\tau \tau_1}} \simeq \sqrt{\frac{Z_0}{R_F \tau \tau_1}} \; , \; Q = \sqrt{\frac{\tau}{\tau_1}} \sqrt{\frac{R_F}{Z_0}}$$

An attempt to increase the bandwidth clearly increases the Q, as does an attempt to overcompensate the amplifier. The break frequency now varies with the square root of R_F , and the gain-bandwidth product is:

$$GBP = \frac{Z_0 G_0}{R_F + Z_0 + G_0 R_0} \sqrt{\frac{Z_0}{R_F \tau \tau_1}} \simeq \sqrt{\frac{Z_0 G_0}{R_F \tau \tau_1}} \text{ much closer to a constant.}$$

Answers - Q4 - Q6 - 15 pages Question 4 Current-mode Analogue SP Page 1/15 a) Assurptions & Conditions [Bookwork] equal number of CW & ACW upn junctions -1- -1- -V- -ON 7 4CN pap -1-Same Vy (i.e. temperature) for all derices All upu (pup) devices have some convent density Isn (15p) When the above hold: cw 5 Vbs; = 4cw 5 Vbe; => => cw \(\frac{5}{J_{\infty}} \) = A(w) \(\frac{5}{J_{\infty}} \) => $=> \qquad \text{CW} \prod_{j=1}^{m} \left[\frac{J_{c_{j}}}{J_{s_{j}}A_{j}} \right] = ACW \prod_{j=1}^{m} \left[\frac{J_{c_{j}}}{J_{s_{i}}A_{j}} \right] =>$ => $(w) \prod_{j=1}^{m} \left[\frac{I_{c_{j}}}{A_{j}}\right] = A(w) \prod_{j=1}^{m} \left[\frac{I_{c_{j}}}{A_{j}}\right] \underbrace{3uuuks}$ b) MOS TLP: $(w) = \sqrt{\frac{I_{0j}}{K_{i}}} = A(w) = \sqrt{\frac{I_{0j}}{K_{j}}}$ [Bukwork] $S = \frac{\mu(ox)}{2} \left(\frac{w}{L}\right)$ - "Sum of work" is not as modely useful as Diahoutages: - MOS square law holds over a smaller current vocage them the bipilow experiental law - poiess parameters do not consel prios) The luops

Administration : MOS TL circuits do not suffer from better errors. (2 months)

i)
$$I_3 + I_4 = I$$

$$\left[\frac{I - I_x}{3}\right]^2 I_4 = I_3 \left[\frac{I + I_x}{3}\right]^2 \Rightarrow \frac{I_4}{I_3} = \left[\frac{I + I_x}{I - I_x}\right]^2$$

$$\frac{I_4 + I_3}{I_3} = \frac{I}{\overline{I}_3} = \frac{\left[I + I_{\times}\right]^2 + \left[I - I_{\times}\right]^2}{\left[I - I_{\times}\right]^2} = 7$$

$$I_3 = \frac{\left[I - I_{\times}\right]^2 I}{\left[I + I_{\times}\right]^2 + \left[I - I_{\times}\right]^2}$$

$$I_{4} = \frac{\left[\int + I_{x} \right]^{2} \mathbf{I}}{\left[\mathbf{I} + \mathbf{J}_{x} \right]^{2} + \left[\mathbf{I} - \mathbf{J}_{x} \right]^{2}}$$

3 months

$$I_{2} = I_{4} + \frac{\Gamma - I_{x}}{3} = \frac{I - I_{x}}{3} + \frac{[I + I_{x}]^{2}I}{[I + I_{x}]^{2}+[I - I_{x}]^{2}}$$

$$I_{1} = I_{3} + \frac{I + I_{x}}{3} = \frac{I + I_{x}}{3} + \frac{[I - I_{x}]^{2}I}{[I + I_{x}]^{2}+[J - I_{x}]^{2}}$$

$$I_{2} - I_{1} = -\frac{2I_{x}}{3} + \frac{[I + I_{x}]^{2}+2I_{x} - I_{x}^{2}+2I_{x}^{2}}{I^{2}+I_{x}^{2}+2I_{x}^{2}+2I_{x}^{2}+2I_{x}^{2}} = \frac{24I_{x}}{3} + \frac{4I_{x}I_{x}}{2I_{x}^{2}+I_{x}^{2}+I_{x}^{2}+I_{x}^{2}+I_{x}^{2}+I_{x}^{2}+I_{x}^{2}} = \frac{44I_{x}I_{x}}{3} + \frac{44I_{x}I_{x}}{2I_{x}^{2}+I_{x$$

d)
i) Applying the TLP
$$\times$$
 KCL yields:

$$(2I+\Gamma_X+\Gamma_Z) \times I = (0.95I+\Gamma_Z) (\Gamma+\Gamma_X) \Rightarrow$$

$$\Rightarrow I_2 = \frac{(2I+\Gamma_X+\Gamma_Z)\Gamma}{\Gamma+\Gamma_X} - 0.95I \qquad \text{2 mealls}$$
ii)

$$TLP \Rightarrow$$

$$\frac{\Gamma_2}{A} = \frac{0.4\Gamma}{A} = \frac{(\Gamma+\Gamma_X)\left[4\Gamma-(\Gamma+\Gamma_X)\right]}{A} \Rightarrow \frac{(\Gamma+\Gamma_X)\Gamma}{\Gamma+\Gamma_X} = 0.95\Gamma = A^2(3\Gamma-\Gamma_X) \Rightarrow$$

$$\Rightarrow (2\Gamma+\Gamma_X+\Gamma_Z)\Gamma = 0.95\Gamma = A^2(3\Gamma-\Gamma_X) \Rightarrow 0.95\Gamma \Rightarrow$$

$$\Rightarrow \frac{\left(2I+I_X+I_Z\right)I}{\left(I+I_X\right)} = \frac{A^2\left(J+I_X\right)\left(3I-J_X\right)}{0.7I} + 0.95I \Rightarrow$$

$$= \frac{1+I_{x}+I_{z}}{I} = \frac{1+I_{x}}{I} \frac{A^{2}(1+I_{x})(3I-I_{x})+0.665I^{2}}{0.7I}$$

$$= \sum_{Z=0}^{2} \int_{Z=0}^{2} \frac{A^{2} (I+I_{x})^{2} (3I-I_{x}) + 0.66 \leq J^{2} (I+J_{x})}{0.7 J^{2}} - 2I - J_{x}}{0.7 J^{2}}$$

$$I_{z} = \frac{A^{2}(I^{2}+I_{x}^{2}+2II_{x})(3I-I_{x})+0.665I^{2}(I+I_{x})-1.4I^{2}-0.7I^{2}I_{x}}{0.7I^{2}} \Rightarrow$$

$$= \sum_{z=1}^{\infty} I_{z} = \left(\frac{3A^{2} - 0.735}{0.7}\right)I + \left(\frac{5A^{2} - 0.035}{0.7}\right)I_{x} + \frac{A^{2}}{0.7}\left[\frac{I_{x}^{2}}{I} - \frac{I_{x}^{3}}{I^{2}}\right]$$

$$I_Z = 1.05 I + 3.45 J_X + 0.4 \left[\frac{J_X^2}{I} - \frac{I_X^3}{I^2} \right]$$

(3 months)

[Exercise bossed on trught material]

PRS

$$a/i)$$
 $y = g(v_c)$

$$\Rightarrow \frac{dY}{dt} = KX \Rightarrow \frac{dY}{dV_c} \dot{V_c} = KX \Rightarrow$$

$$= \frac{dy(V_c)}{dV_c} \frac{f(x)}{c} = kx = >$$

$$= > \left\{ \frac{dy(v_c)}{w_c} \frac{f(x)}{c} = k \times \right\} = >$$

$$f(x) = \frac{KCX}{dg(V_E)}$$

$$\frac{dg(V_E)}{dg(V_E)}$$

$$\frac{d\rho(V_c)}{dV_c} = \frac{I_T}{V_T} \frac{\operatorname{sech}(\alpha V_c)}{\operatorname{sech}(\alpha V_c)} = \frac{I_T}{V_T} \frac{1}{\cosh^2(\alpha V_c)}$$

$$\frac{dg(V_c)}{dV_c} = \frac{I_T}{V_T} \frac{\operatorname{sech}(eV_c)}{\operatorname{de}(V_c)} = \frac{I_T}{V_T} \frac{1}{\operatorname{ush}^2(aV_c)} \Rightarrow \frac{1}{2\operatorname{muv}(V_s)}$$

$$\frac{dg(V_c)}{dV_c} = \frac{I_T}{V_T} \left[1 - \operatorname{tauh}(aV_c) \right] = \frac{I_T}{V_T} \left[\frac{I_T^2 - Y^2}{I_T^2} \right] \Rightarrow V_T$$

$$f(x) = \frac{k(x)}{\frac{J_T^2 - y^2}{y^2 - y^2}} = \frac{k(x)}{\frac{J_T^2 - y^2}{y^2 - y^2}}$$

$$x_1 + w_0 x_1 - w_0 x_2 = 0$$

 $2w_0 x_1 + x_2 - w_0 x_2 = w_0 V(t)$
 $y = x_1$

$$\int = \left| \begin{array}{cc} S + W_0 & -W_0 \\ 2W_0 & -W_0 \end{array} \right| = S^2 - W_0^2 + 2W_0^2 = S^2 + W_0^2$$

$$D_{X_{\perp}} = \left| \begin{array}{c} 0 & -\omega_0 \\ \omega_0 \mathcal{V}(\omega) & (s-\omega_0) \end{array} \right| = \left| \omega_0^2 \mathcal{V}(\omega) \right|$$

$$=> X_{1}(s) = \frac{m^{2}}{s^{2}+w_{0}^{2}} \mathcal{J}(s) \Rightarrow \frac{X_{1}(s)[=X(s)]}{\mathcal{J}(s)} = \frac{w_{0}^{2}}{s^{2}+w_{0}^{2}}$$

3 musk

$$ii) \quad \chi_{1} = I_{1} e^{\frac{\sqrt{2}}{V_{T}}} \Rightarrow \chi_{1} = \chi_{1} \frac{\sqrt{i}}{V_{T}}$$

$$\chi_{2} = I_{2} e^{\frac{\sqrt{2}}{V_{T}}} \Rightarrow \chi_{2} = \chi_{2} \frac{\sqrt{i}}{V_{T}}$$

$$\int = I_{u} e^{\frac{\sqrt{i}}{V_{T}}} + w_{0} \times \chi - w_{0} \times \chi_{2} = 0$$

$$\chi \frac{\sqrt{i}}{V_{T}} + w_{0} \times \chi - w_{0} \times \chi_{2} = 0$$

$$\chi \frac{\sqrt{i}}{V_{T}} + w_{0} \times \chi - w_{0} \times \chi_{2} = 0$$

$$\chi \frac{\sqrt{i}}{V_{T}} + w_{0} \times \chi - w_{0} \times \chi_{2} = 0$$

$$\chi \frac{\sqrt{i}}{V_{T}} + \chi_{2} \frac{\sqrt{i}}{V_{T}} - w_{0} \times \chi_{2} = w_{0} \frac{V(t)}{X_{2}}$$

$$\int CV_{1} + (CV_{T}w_{0}) = (V_{2}w_{0}) \frac{I_{2}}{I_{1}} e^{\frac{V_{2}-V_{1}}{V_{T}}}$$

$$CV_{2} + 2(CV_{T}w_{0}) \frac{I_{3}}{I_{2}} e^{\frac{V_{3}-V_{3}}{V_{T}}} = (CV_{T}w_{0}) + (CV_{T}w_{0}) \frac{I_{3}}{I_{2}} e^{\frac{V_{3}-V_{3}}{V_{T}}}$$

$$\int CV_{1} + I_{1} = I_{2} = I_{0} \times I_{1} = I_{2} = 3$$

$$\int CV_{1} + I_{1} = I_{2} = I_{0} \times I_{1} = I_{2} = 3$$

$$\frac{V_2 - V_4}{V_T}$$

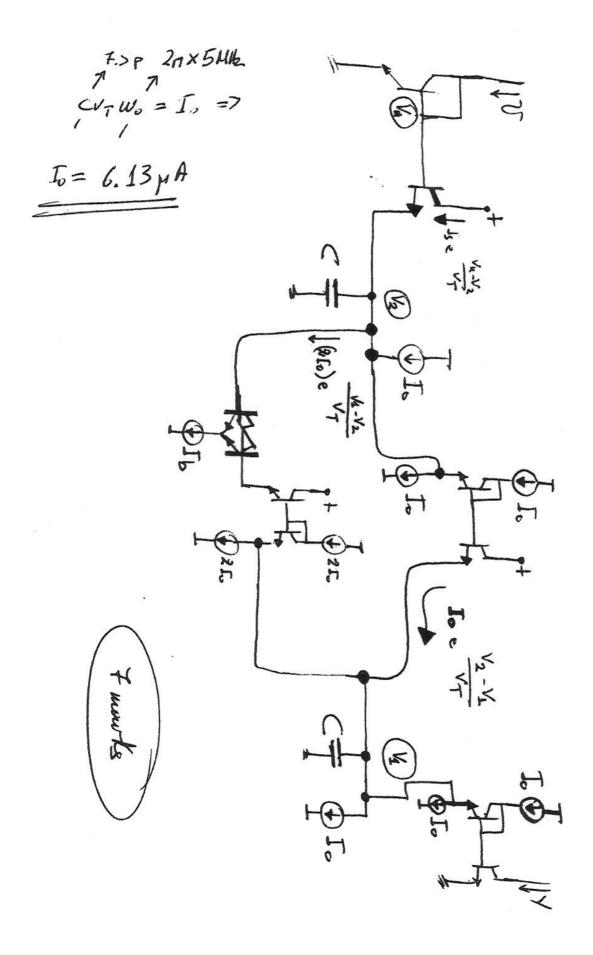
$$= \frac{V_2 - V_4}{V_7}$$

$$= \frac{V_4 + I_0}{V_7} = \frac{V_4 - V_2}{V_7} = \frac{V_4 - V_2}{V_7}$$

$$= \frac{V_4 - V_2}{V_7} = \frac{V_4 - V_2}{V_7} = \frac{V_4 - V_2}{V_7}$$

$$Y = X_1 = I_0 e^{V_2 V_T}$$

$$\frac{(V_T W_0 = I_0)}{(6 \text{ mow } K_S)}$$



a) Two N-port networks A & B must satisfy the following relation in order to be adjoint:

with Van Sensting the voltage of the n-th port of network A, etc.

Resistor VA = RAIA, one port

$$V_A \Gamma_B - V_B \Gamma_A = 0 \implies \frac{V_B}{\Gamma_B} = \frac{V_A}{\Gamma_A} \implies V_B = \frac{\Gamma_B}{\Gamma_B} = > V_B = \frac{V_B}{\Gamma_B} = \frac{V_B}{\Gamma_B} =$$

=> the adjoint of experience is a resistor of the some value RA \$ <=> \$ RB (= RA)

Nullar Fort2
$$V_A = [V_{A1} \ V_{A2}] = [0 \ \times]$$

$$\Gamma_A = [\Gamma_{A1} \ \Gamma_{A2}] = [0 \ \times]$$

$$V_A = [V_{A1} \ V_{A2}] = [0 \ \times]$$

$$V_A = [V_{A1} \ V_{A2}] = [0 \ \times]$$

$$V_A = [V_{A1} \ V_{A2}] = [0 \ \times]$$

X denstes "our value"

Have I want: VAL IBI-VBI IAI + VAZ IBZ-VBZ IAZ = 0

and IB=[IBi SB2] = [x,0] the relation is while Hence when Vg=[VB1 VB2] = [× 0] Thus, the adjoint of a uller is another suller with its input & autput purts interchanged

input A. Millor output <=> output B input

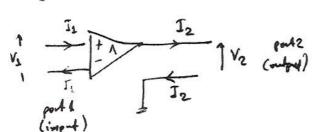
port

port

(2)

(2)

(2)



$$V_A = [V_A, V_{A2}] = [V_{in}, AV_{in}]$$

$$I_A = [I_A, I_{A2}] = [Q, \times]$$

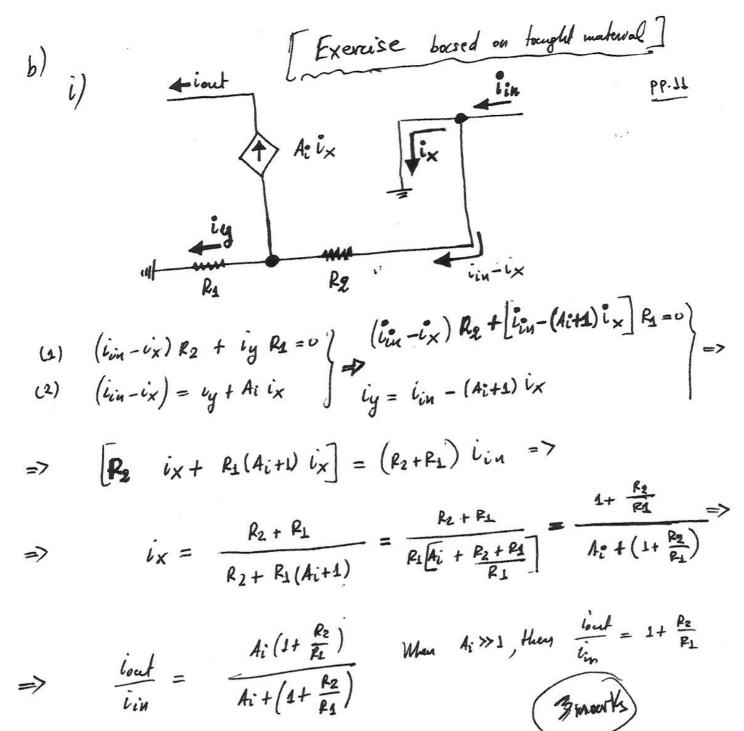
when

$$V_B = [V_{B_\perp} V_{B_2}] = [\times 0]$$

$$I_B = [I_{B_\perp} I_{B_\perp}] = [-AI_{in} I_{in}] \quad \text{then the relations}$$

is suchished

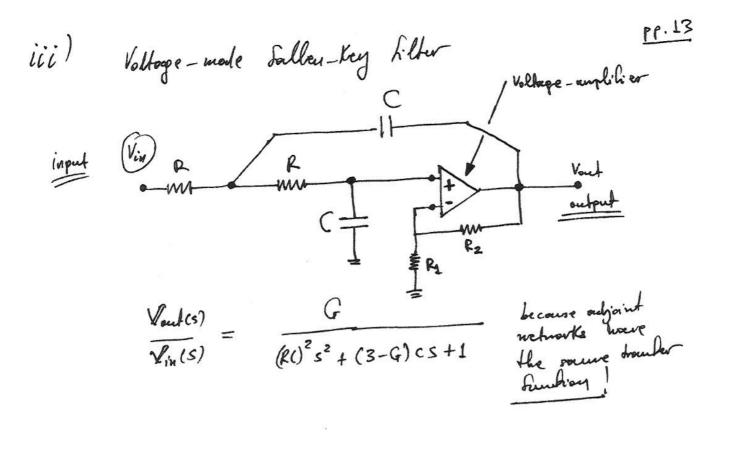
Thus, the adjoint of our ideal rollinge surphilier a ment amplifier with input & and put interchanged:



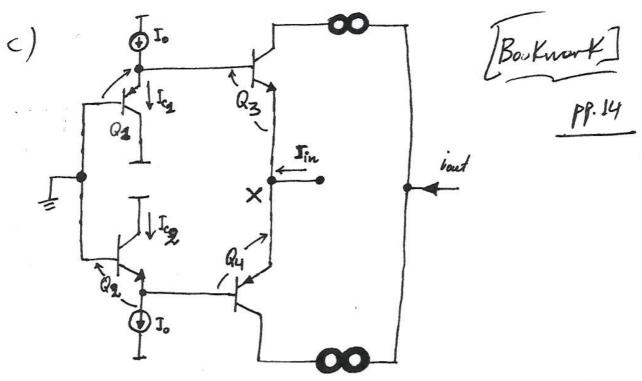
When
$$A_{i} \gg 1$$
 \Rightarrow $i_{1} = GI = G(i_{1h} - i_{2}) \Rightarrow P(1)^{2}$
 $\downarrow_{b} = G(i_{1h} + cv_{\infty}) \Rightarrow [i_{1}(s) = G[i_{1h}(t) + cs_{1h}(s)]$
 $\downarrow_{b} = G(i_{1h} + cv_{\infty}) \Rightarrow [i_{1}(s) = G[i_{1h}(t) + cs_{1h}(s)]$
 $\downarrow_{c} = cv_{\infty} + \frac{v_{\infty} - v_{b}}{R} \Rightarrow cv_{\infty} + \frac{v_{\infty} - v_{b}}{R} \Rightarrow cv_{\infty} + cv_{\infty} \Rightarrow \frac{v_{\infty}(s)}{R} = \frac{2}{R} + cs_{\infty} V_{\infty}(s) \Rightarrow cs_{\infty} + cv_{\infty} + cv_{\infty} \Rightarrow \frac{v_{\infty}(s)}{R} + cv_{\infty} \Rightarrow \frac{v_{\infty}(s)}{R} + cv_{\infty} \Rightarrow \frac{v_{\infty}(s)}{R} + cv_{\infty}(s) = \frac{1}{R} + cs_{\infty} V_{\infty}(s) \Rightarrow cs_{\infty} + cv_{\infty}(s) + R \cdot i_{\infty}(s) = [1 + RCs] V_{\infty}(s)$

Substituting (1) \Rightarrow (2) into (3):

 $V_{\alpha}(s) + R \cdot G[i_{\infty}(s) + cs_{\infty}(s)] = [1 + Rcs_{\infty}] V_{\infty}(s) \Rightarrow cs_{\infty} + cv_{\infty}(s) \Rightarrow cs_{\infty}(s) \Rightarrow cs$



1mar 4



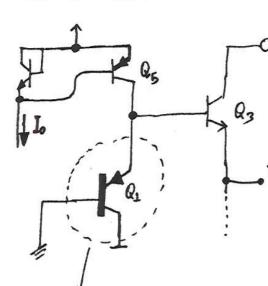
When
$$I_{in} = 0$$
, $I_{C_3} = I_{C_4}$ (assuming inhimite below) $I_{C_3} = I_{C_4}$ (by $I_{C_4} = I_{C_5} = I_{C_5} = I_{C_4}$) $I_{C_4} = I_{C_5} = I_{C_5} = I_{C_4}$

$$=>$$
 $I_{C_3}=I_{C_4}=I_0$

D(offset whose
$$V_{offset} (\equiv V_{X}) + V_{beg} - V_{beg} = 0 \Rightarrow$$
 $\Rightarrow V_{offset} = V_{beg} - V_{beg} = V_{T} \ln \left(\frac{I_{o}}{I_{sp}} \frac{I_{sh}}{I_{o}}\right) = 0 \Rightarrow$
 $\Rightarrow V_{offset} = V_{T} \ln \left(\frac{I_{sy}}{I_{sp}}\right)$
 $\Rightarrow V_{offset} = V_{T} \ln \left(\frac{I_{sy}}{I_{sp}}\right)$

2 mourts

iii)



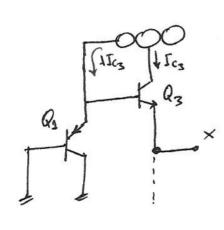
$$V_{6e6} = V_{7} lu \left(\frac{I_{0}}{I_{y}} \right)$$

$$I_{C_{5}} = I_{5p} e \frac{V_{7} lu \left(\frac{I_{0}}{I_{5u}} \right)}{V_{7}} =>$$

$$= V_{T} \ln \left(\frac{I_{C_{1}}}{I_{S_{p}}} \right) - V_{T} \ln \left(\frac{I_{0}}{I_{S_{1}}} \right) =$$

$$= \left(V_{T} \ln \left(\frac{I_{0}}{I_{S_{p}}} \right) - V_{T} \ln \left(\frac{I_{0}}{I_{S_{1}}} \right) \right) - V_{T} \ln \left(\frac{I_{0}}{I_{S_{1}}} \right) =$$

Use of local aurent feedback



$$R_{x} = \frac{V_{x}}{J_{x}} = \frac{V_{be1} - V_{bi3}}{J_{x}} \Rightarrow$$

$$R_{x} = \frac{V_{x} \ln \left(\frac{J_{x}}{J_{x}} \frac{J_{x}}{J_{x}}\right)}{J_{x}} \Rightarrow$$

$$R_{x} = V_{x} \ln \left(\frac{J_{x}}{J_{x}} \frac{J_{x}}{J_{x}}\right) \Rightarrow$$

$$V_{be1} - V_{be3} = v_{x} \omega_{x} \delta_{x} \omega_{x} \omega_{x}$$