

PART - I**TYPICAL QUESTIONS & ANSWERS****OBJECTIVE TYPE QUESTIONS**

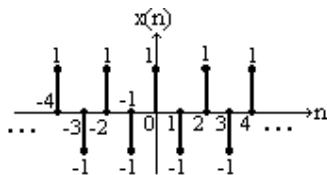
Each Question carries 2 marks.

Choose the correct or best alternative in the following:

Q.1 The discrete-time signal $x(n) = (-1)^n$ is periodic with fundamental period

- | | |
|-------|-------|
| (A) 6 | (B) 4 |
| (C) 2 | (D) 0 |

Ans: C Period = 2

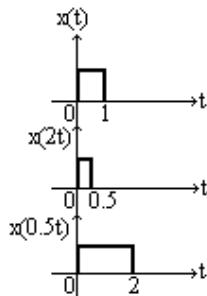


Q.2 The frequency of a continuous time signal $x(t)$ changes on transformation from $x(t)$ to $x(\alpha t)$, $\alpha > 0$ by a factor

- | | |
|------------------|--------------------------|
| (A) α . | (B) $\frac{1}{\alpha}$. |
| (C) α^2 . | (D) $\sqrt{\alpha}$. |

Ans: A $x(t) \xrightarrow{\text{Transform}} x(\alpha t), \alpha > 0$

$\alpha > 1 \Rightarrow$ compression in t , expansion in f by α .
 $\alpha < 1 \Rightarrow$ expansion in t , compression in f by α .



Q.3 A useful property of the unit impulse $\delta(t)$ is that

- | | |
|--|------------------------------------|
| (A) $\delta(at) = a \delta(t)$. | (B) $\delta(at) = \delta(t)$. |
| (C) $\delta(at) = \frac{1}{a} \delta(t)$. | (D) $\delta(at) = [\delta(t)]^a$. |

Ans: C Time-scaling property of $\delta(t)$:

$$\delta(at) = \frac{1}{a} \delta(t), a > 0$$

Q.4 The continuous time version of the unit impulse $\delta(t)$ is defined by the pair of relations

(A) $\delta(t) = \begin{cases} 1 & t=0 \\ 0 & t \neq 0 \end{cases}$ (B) $\delta(t) = 1, t=0$ and $\int_{-\infty}^{\infty} \delta(t) dt = 1$.

(C) $\delta(t) = 0, t \neq 0$ and $\int_{-\infty}^{\infty} \delta(t) dt = 1$. (D) $\delta(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$

Ans: C $\delta(t) = 0, t \neq 0 \rightarrow \delta(t) \neq 0$ at origin

$$\int_{-\infty}^{+\infty} \delta(t) dt = 1 \rightarrow \text{Total area under the curve is unity.}$$

[$\delta(t)$ is also called Dirac-delta function]

Q.5 Two sequences $x_1(n)$ and $x_2(n)$ are related by $x_2(n) = x_1(-n)$. In the z-domain, their ROC's are

(A) the same.

(B) reciprocal of each other.

(C) negative of each other.

(D) complements of each other.

Ans: B $x_1(n) \xleftrightarrow[z]{\quad} X_1(z), \text{RoC } R_x$

$x_2(n) = x_1(-n) \xleftrightarrow[z]{\quad} X_1(1/z), \text{RoC } 1/R_x$

$\left. \begin{array}{l} \\ \end{array} \right\} \text{Reciprocals}$

Q.6 The Fourier transform of the exponential signal $e^{j\omega_0 t}$ is

(A) a constant.

(B) a rectangular gate.

(C) an impulse.

(D) a series of impulses.

Ans: C Since the signal contains only a high frequency ω_0 its FT must be an impulse at $\omega = \omega_0$

Q.7 If the Laplace transform of $f(t)$ is $\frac{\omega}{s^2 + \omega^2}$, then the value of $\lim_{t \rightarrow \infty} f(t)$

(A) cannot be determined. (B) is zero.

(C) is unity. (D) is infinity.

Ans: B $f(t) \xleftrightarrow[L]{\quad} \frac{\omega}{s^2 + \omega^2}$

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} s F(s) \quad [\text{Final value theorem}]$$

$$= \lim_{s \rightarrow 0} \left(\frac{s\omega}{s^2 + \omega^2} \right) = 0$$

Q.8 The unit impulse response of a linear time invariant system is the unit step function $u(t)$. For $t > 0$, the response of the system to an excitation

$e^{-at} u(t)$, $a > 0$, will be

(A) ae^{-at} .

(B) $\frac{1-e^{-at}}{a}$.

(C) $a(1-e^{-at})$.

(D) $1-e^{-at}$.

Ans: B

$$h(t) = u(t); \quad x(t) = e^{-at} u(t), \quad a > 0$$

$$\begin{aligned} \text{System response } y(t) &= L^{-1} \left[\frac{1}{s} \cdot \frac{1}{s+a} \right] \\ &= L^{-1} \frac{1}{a} \left[\frac{1}{s} - \frac{1}{s+a} \right] \\ &= \frac{1}{a} (1 - e^{-at}) \end{aligned}$$

Q.9 The z-transform of the function $\sum_{k=-\infty}^0 \delta(n-k)$ has the following region of convergence

(A) $|z| > 1$

(B) $|z| = 1$

(C) $|z| < 1$

(D) $0 < |z| < 1$

Ans: C $x(n) = \sum_{k=-\infty}^0 \delta(n-k)$

$$x(z) = \sum_{k=-\infty}^0 z^{-k} = \dots + z^3 + z^2 + z + 1 \quad (\text{Sum of infinite geometric series})$$

$$= \frac{1}{1-z}, \quad |z| < 1$$

Q.10 The auto-correlation function of a rectangular pulse of duration T is

(A) a rectangular pulse of duration T.

(B) a rectangular pulse of duration 2T.

(C) a triangular pulse of duration T.

(D) a triangular pulse of duration 2T.

Ans: D

$$R_{XX}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} x(\tau) x(t+\tau) dt \Leftrightarrow \text{triangular function of duration } 2T.$$

Q.11 The Fourier transform (FT) of a function $x(t)$ is $X(f)$. The FT of $dx(t)/dt$ will be

- (A) $dX(f)/df$.
- (B) $j2\pi f X(f)$.
- (C) $jf X(f)$.
- (D) $X(f)/(jf)$.

$$\text{Ans: } B(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(f) e^{j\omega t} d\omega$$

$$\begin{aligned} \frac{d_x}{dt} &= \frac{1}{2\pi} \int_{-\infty}^{\infty} j\omega X(f) e^{j\omega t} d\omega \\ \therefore \frac{d_x}{dt} &\leftrightarrow j 2\pi f X(f) \end{aligned}$$

Q.12 The FT of a rectangular pulse existing between $t = -T/2$ to $t = T/2$ is a

- (A) sinc squared function.
- (B) sinc function.
- (C) sine squared function.
- (D) sine function.

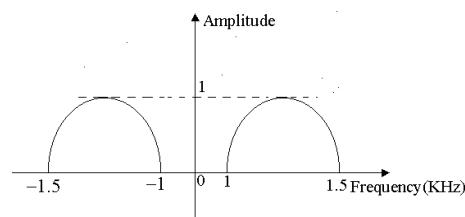
$$\text{Ans: } Bx(t) = \begin{cases} 1, & -\frac{T}{2} \leq t \leq \frac{T}{2} \\ 0, & \text{otherwise} \end{cases}$$

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt = \int_{-T/2}^{+T/2} e^{-j\omega t} dt = \left. \frac{e^{-j\omega t}}{j\omega} \right|_{-T/2}^{+T/2} \\ &= -\frac{1}{j\omega} (e^{-j\omega T/2} - e^{j\omega T/2}) = \frac{2}{\omega} \left(\frac{e^{j\omega T/2} - e^{-j\omega T/2}}{2j} \right) \\ &= \frac{2 \sin \frac{\omega T}{2}}{\omega} = \frac{\sin(\omega T/2)}{\omega T/2} \cdot T \end{aligned}$$

Hence $X(j\omega)$ is expressed in terms of a sinc function.

Q.13 An analog signal has the spectrum shown in Fig. The minimum sampling rate needed to completely represent this signal is

- (A) 3 KHz.
- (B) 2 KHz.
- (C) 1 KHz.
- (D) 0.5 KHz.



Ans: C For a band pass signal, the minimum sampling rate is twice the bandwidth, which is 0.5kHz here.

Q.14 A given system is characterized by the differential equation:

$$\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} - 2y(t) = x(t).$$

The system is :

- | | |
|-----------------------------|---------------------------|
| (A) linear and unstable. | (B) linear and stable. |
| (C) nonlinear and unstable. | (D) nonlinear and stable. |

Ans:A $\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} - 2y(t) = x(t)$, $x(t) \rightarrow \boxed{h(t)}$ $\rightarrow y(t)$

The system is linear . Taking LT with zero initial conditions, we get
 $s^2Y(s) - sY(s) - 2Y(s) = X(s)$

$$\text{or, } H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 - s - 2} = \frac{1}{(s-2)(s+1)}$$

Because of the pole at $s = +2$, the system is unstable.

Q.15 The system characterized by the equation $y(t) = ax(t) + b$ is

- | | |
|--------------------------------|-------------------------|
| (A) linear for any value of b. | (B) linear if $b > 0$. |
| (C) linear if $b < 0$. | (D) non-linear. |

Ans: D The system is non-linear because $x(t) = 0$ does not lead to $y(t) = 0$, which is a violation of the principle of homogeneity.

Q.16 Inverse Fourier transform of $u(\omega)$ is

- | | |
|--|-----------------------------------|
| (A) $\frac{1}{2}\delta(t) + \frac{1}{\pi t}$. | (B) $\frac{1}{2}\delta(t)$. |
| (C) $2\delta(t) + \frac{1}{\pi t}$. | (D) $\delta(t) + \text{sgn}(t)$. |

Ans: A $x(t) = u(t) \xleftrightarrow{\text{FT}} X(j\omega) = \pi \frac{\delta(\omega)}{j\omega} + 1$

Duality property: $X(jt) \longleftrightarrow 2\pi x(-\omega)$

$$u(\omega) \longleftrightarrow \frac{1}{2}\delta(t) + \frac{1}{\pi t}$$

Q.17 The impulse response of a system is $h(n) = a^n u(n)$. The condition for the system to be BIBO stable is

- (A) a is real and positive. (B) a is real and negative.
 (C) $|a| > 1$. (D) $|a| < 1$.

Ans: D Sum S = $\sum_{n=-\infty}^{+\infty} |h(n)| = \sum_{n=-\infty}^{+\infty} |a^n u(n)|$

$$\leq \sum_{n=0}^{+\infty} |a|^n \quad (\because u(n) = 1 \text{ for } n \geq 0)$$

$$\leq \frac{1}{1-|a|} \quad \text{if } |a| < 1.$$

Q.18 If R_1 is the region of convergence of $x(n)$ and R_2 is the region of convergence of $y(n)$, then the region of convergence of $x(n)$ convoluted $y(n)$ is

- (A) $R_1 + R_2$. (B) $R_1 - R_2$.
 (C) $R_1 \cap R_2$. (D) $R_1 \cup R_2$.

Ans:C $x(n) \xleftrightarrow{z} X(z), \text{ RoC } R_1$
 $y(n) \xleftrightarrow{z} Y(z), \text{ RoC } R_2$
 $x(n) * y(n) \xleftrightarrow{z} X(z).Y(z), \text{ RoC at least } R_1 \cap R_2$

Q.19 The continuous time system described by $y(t) = x(t^2)$ is

- (A) causal, linear and time varying.
 (B) causal, non-linear and time varying.
 (C) non causal, non-linear and time-invariant.
 (D) non causal, linear and time-invariant.

Ans: D

$$y(t) = x(t^2)$$

$y(t)$ depends on $x(t^2)$ i.e., future values of input if $t > 1$.

\therefore System is anticipative or non-causal

$$\alpha x_1(t) \rightarrow y_1(t) = \alpha x_1(t^2)$$

$$\beta x_2(t) \rightarrow y_2(t) = \beta x_2(t^2)$$

$$\therefore \alpha x_1(t) + \beta x_2(t) \rightarrow y(t) = \alpha x_1(t^2) + \beta x_2(t^2) = y_1(t) + y_2(t)$$

\therefore System is Linear

System is time varying. Check with $x(t) = u(t) - u(t-1) \rightarrow y(t)$ and

$$x_1(t) = x(t-1) \rightarrow y_1(t) \text{ and find that } y_1(t) \neq y(t-1).$$

Q.20 If $G(f)$ represents the Fourier Transform of a signal $g(t)$ which is real and odd symmetric in time, then $G(f)$ is

- (A) complex.
- (B) imaginary.
- (C) real.
- (D) real and non-negative.

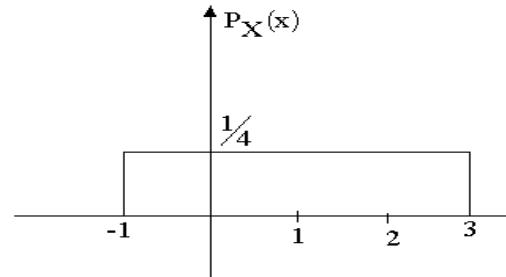
$$\text{Ans:B } g(t) \xleftrightarrow{\text{FT}} G(f)$$

$g(t)$ real, odd symmetric in time

$G^*(j\omega) = -G(j\omega)$; $G(j\omega)$ purely imaginary.

Q.21 For a random variable x having the PDF shown in the Fig., the mean and the variance are, respectively,

- (A) $\frac{1}{2}$ and $\frac{2}{3}$.
- (B) 1 and $\frac{4}{3}$.
- (C) 1 and $\frac{2}{3}$.
- (D) 2 and $\frac{4}{3}$.



$$\begin{aligned} \text{Ans:B Mean} &= \mu_x(t) = \int_{-\infty}^{+\infty} x f_{x(t)}(x) dx \\ &= \int_{-1}^3 x \frac{1}{4} dx = \frac{1}{4} \frac{x^2}{2} \Big|_{-1}^3 = \left[\frac{9}{2} - \frac{1}{2} \right] \frac{1}{4} = 1 \end{aligned}$$

$$\begin{aligned} \text{Variance} &= \int_{-\infty}^{+\infty} (x - \mu_x)^2 f_x(x) dx \\ &= \int_{-1}^3 (x - 1)^2 \frac{1}{4} d(x-1) \\ &= \frac{1}{4} \frac{(x-1)^3}{3} \Big|_{-1}^3 = \frac{1}{12} [8 + 8] = \frac{4}{3} \end{aligned}$$

Q.22 If white noise is input to an RC integrator the ACF at the output is proportional to

- (A) $\exp\left(\frac{-|\tau|}{RC}\right)$. (B) $\exp\left(\frac{-\tau}{RC}\right)$.
 (C) $\exp(|\tau|RC)$. (D) $\exp(-\tau RC)$.

Ans: A

$$R_N(\tau) = \frac{N_0}{4RC} \left[\exp - \left| \frac{\tau}{RC} \right| \right]$$

Q.23 $x(n) = a^{|n|}$, $|a| < 1$ is

- (A) an energy signal.
 (B) a power signal.
 (C) neither an energy nor a power signal.
 (D) an energy as well as a power signal.

Ans: A

$$\text{Energy} = \sum_{n=-\infty}^{+\infty} x^2(n) = \sum_{n=-\infty}^{\infty} a^{2|n|} = \sum_{n=-\infty}^{\infty} (a^2)^{|n|} = 1 + 2 \sum_{n=1}^{\infty} a^2$$

$$= \text{finite since } |a| < 1$$

\therefore This is an energy signal.

Q.24 The spectrum of $x(n)$ extends from $-\omega_0$ to $+\omega_0$, while that of $h(n)$ extends

from $-2\omega_0$ to $+2\omega_0$. The spectrum of $y(n) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$ extends

from

- (A) $-4\omega_0$ to $+4\omega_0$. (B) $-3\omega_0$ to $+3\omega_0$.
 (C) $-2\omega_0$ to $+2\omega_0$. (D) $-\omega_0$ to $+\omega_0$

Ans: D Spectrum depends on $H(e^{j\omega}) \rightarrow X(e^{j\omega})$ Smaller of the two ranges.

Q.25 The signals $x_1(t)$ and $x_2(t)$ are both bandlimited to $(-\omega_1, +\omega_1)$ and $(-\omega_2, +\omega_2)$ respectively. The Nyquist sampling rate for the signal $x_1(t)x_2(t)$ will be

- (A) $2\omega_1$ if $\omega_1 > \omega_2$. (B) $2\omega_2$ if $\omega_1 < \omega_2$.
 (C) $2(\omega_1 + \omega_2)$. (D) $\frac{(\omega_1 + \omega_2)}{2}$.

Ans: C Nyquist sampling rate = $2(\text{Bandwidth}) = 2(\omega_1 - (-\omega_2)) = 2(\omega_1 + \omega_2)$

Q.26 If a periodic function $f(t)$ of period T satisfies $f(t) = -f(t + T/2)$, then in its Fourier series expansion,

- (A) the constant term will be zero.
- (B) there will be no cosine terms.
- (C) there will be no sine terms.
- (D) there will be no even harmonics.

Ans:

$$\frac{1}{T} \int_0^T f(t) dt = \frac{1}{T} \left(\int_0^{T/2} f(t) dt + \int_{T/2}^T f(t) dt \right) = \frac{1}{T} \left(\int_0^{T/2} f(t) dt + \int_0^{T/2} f(\tau + T/2) d\tau \right) = 0$$

Q.27 A band pass signal extends from 1 KHz to 2 KHz. The minimum sampling frequency needed to retain all information in the sampled signal is

- | | |
|------------|------------|
| (A) 1 KHz. | (B) 2 KHz. |
| (C) 3 KHz. | (D) 4 KHz. |

Ans: B

$$\text{Minimum sampling frequency} = 2(\text{Bandwidth}) = 2(1) = 2 \text{ kHz}$$

Q.28 The region of convergence of the z-transform of the signal

- $$2^n u(n) - 3^n u(-n-1)$$
- | | |
|------------------------|---------------------|
| (A) is $ z > 1$. | (B) is $ z < 1$. |
| (C) is $2 < z < 3$. | (D) does not exist. |

Ans:

$$2^n u(n) \leftrightarrow \frac{1}{1 - 2z^{-1}}, \quad |z| > 2$$

$$3^n u(-n-1) \leftrightarrow \frac{1}{1 - 3z^{-1}}, \quad |z| < 3$$

\therefore ROC is $2 < |z| < 3$.

Q.29 The number of possible regions of convergence of the function $\frac{(e^{-2} - 2)z}{(z - e^{-2})(z - 2)}$ is

- | | |
|--------|--------|
| (A) 1. | (B) 2. |
| (C) 3. | (D) 4. |

Ans: C

Possible ROC's are $|z| > e^{-2}$, $|z| < 2$ and $e^{-2} < |z| < 2$

Q.30 The Laplace transform of $u(t)$ is $A(s)$ and the Fourier transform of $u(t)$ is $B(j\omega)$.

Then

$$(A) B(j\omega) = A(s)|_{s=j\omega} . \quad (B) A(s) = \frac{1}{s} \text{ but } B(j\omega) \neq \frac{1}{j\omega} .$$

$$(C) A(s) \neq \frac{1}{s} \text{ but } B(j\omega) = \frac{1}{j\omega} . \quad (D) A(s) \neq \frac{1}{s} \text{ but } B(j\omega) \neq \frac{1}{j\omega} .$$

Ans: B $u(t) \xrightarrow{L} A(s) = \frac{1}{s}$

F.T
 $u(t) \xrightarrow{\text{F.T}} B(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$

$$\therefore A(s) = \frac{1}{s} \text{ but } B(j\omega) \neq \frac{1}{j\omega}$$

PART – II**NUMERICALS & DERIVATIONS**

Q.1. Determine whether the system having input $x(n)$ and output $y(n)$ and described by

$$\text{relationship : } y(n) = \sum_{k=-\infty}^n x(k+2)$$

is (i) memoryless, (ii) stable, (iii) causal (iv) linear and (v) time invariant. (5)

Ans:

$$y(n) = \sum_{k=-\infty}^n x(k+2)$$

- (i) Not memoryless - as $y(n)$ depends on past values of input from $x(-\infty)$ to $x(n-1)$ (assuming $n > 0$)
- (ii) Unstable - since if $|x(n)| \leq M$, then $|y(n)|$ goes to ∞ for any n .
- (iii) Non-causal - as $y(n)$ depends on $x(n+1)$ as well as $x(n+2)$.
- (iv) Linear - the principle of superposition applies (due to \sum operation)
- (v) Time – invariant - a time-shift in input results in corresponding time-shift in output.

Q.2. Determine whether the signal $x(t)$ described by

$$x(t) = e^{-at} u(t), a > 0$$

(5)

Ans:

$$x(t) = e^{-at} u(t), a > 0$$

$x(t)$ is a non-periodic signal.

$$\text{Energy } E = \int_{-\infty}^{+\infty} x^2(t) dt = \int_0^{\infty} e^{-2at} dt = \frac{e^{-2at}}{-2a} \Big|_0^{\infty} = \frac{1}{2a} \text{ (finite, positive)}$$

The energy is finite and deterministic.

$\therefore x(t)$ is an energy signal.

Q.3. Determine the even and odd parts of the signal $x(t)$ given by

$$x(t) = \begin{cases} A e^{-\alpha t} & t > 0 \\ 0 & t < 0 \end{cases}$$

$$x(t) = \begin{cases} A e^{-\alpha t} & t > 0 \\ 0 & t < 0 \end{cases}$$

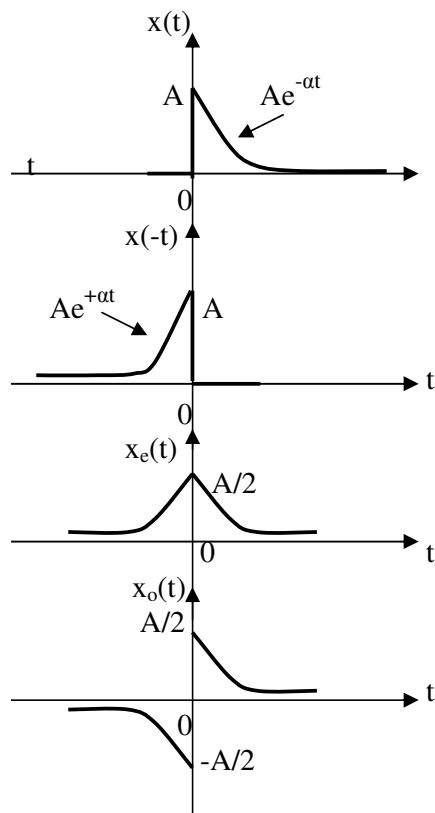
(5)

Ans:

Assumption : $\alpha > 0, A > 0, -\infty < t < \infty$

$$\text{Even part } x_e(t) = \frac{x(t) + x(-t)}{2}$$

$$\text{Odd part } x_o(t) = \frac{x(t) - x(-t)}{2}$$



Q.4. Use one sided Laplace transform to determine the output $y(t)$ of a system described by

$$\frac{d^2y}{dt^2} + 3 \frac{dy}{dt} + 2y(t) = 0 \text{ where } y(0-) = 3 \text{ and } \left. \frac{dy}{dt} \right|_{t=0-} = 1 \quad (7)$$

Ans:

$$\frac{d^2y}{dt^2} + 3 \frac{dy}{dt} + 2y(t) = 0, \quad y(0-) = 3, \quad \left. \frac{dy}{dt} \right|_{t=0^-} = 1$$

$$\left[s^2 Y(s) - s y(0) - \left. \frac{dy}{dt} \right|_{t=0^-} \right] + 3 [s Y(s) - y(0)] + 2 Y(s) = 0$$

$$(s^2 + 3s + 2) Y(s) = s y(0) + \left. \frac{dy}{dt} \right|_{t=0^-} + 3 y(0)$$

$$(s^2 + 3s + 2) Y(s) = 3s + 1 + 9 = 3s + 10$$

$$\begin{aligned} Y(s) &= \frac{3s + 10}{s^2 + 3s + 2} = \frac{3s + 10}{(s + 1)(s + 2)} \\ &= \frac{A}{s + 1} + \frac{B}{s + 2} \end{aligned}$$

$$A = \left. \frac{3s + 10}{s + 2} \right|_{s=-1} = 7 ; \quad B = \left. \frac{3s + 10}{s + 1} \right|_{s=-2} = -4$$

$$\therefore Y(s) = \frac{7}{s+1} - \frac{4}{s+2}$$

$$\therefore y(t) = L^{-1}[Y(s)] = 7e^{-t} - 4e^{-2t} = e^{-t}(7 - 4e^{-t})$$

\therefore The output of the system is $y(t) = e^{-t}(7 - 4e^{-t}) u(t)$

Q. 5. Obtain two different realizations of the system given by

$$y(n) - (a+b)y(n-1) + aby(n-2) = x(n). \text{Also obtain its transfer function.} \quad (7)$$

Ans:

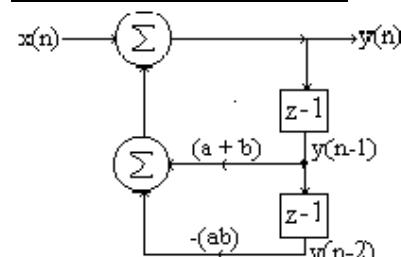
$$y(n) - (a+b)y(n-1) + aby(n-2) = x(n)$$

$$\therefore Y(z) - (a+b)z^{-1}Y(z) + abz^{-2}Y(z) = X(z)$$

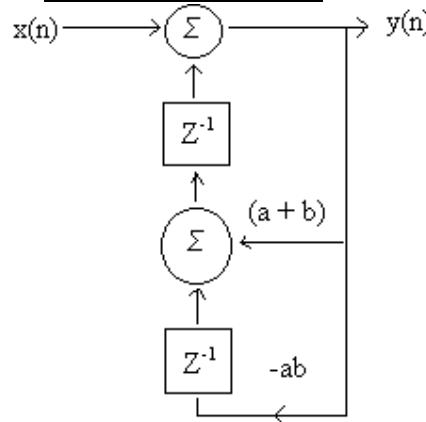
$$\text{Transfer function } H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 - (a+b)z^{-1} + abz^{-2}}$$

$$y(n) = x(n) + (a+b)y(n-1) - aby(n-2)$$

Direct Form I/II realization



Alternative Realisation



Q. 6. An LTI system has an impulse response

$$h(t) = \exp[-at]u(t); \text{ when it is excited by an input signal } x(t), \text{ its output is } y(t) \\ = [\exp(-bt) - \exp(-ct)]u(t) \text{ Determine its input } x(t). \quad (7)$$

Ans:

$$h(t) = e^{-at}u(t) \text{ for input } x(t)$$

$$\text{Output } y(t) = (e^{-bt} - e^{-ct})u(t)$$

$$h(t) \xleftrightarrow{L} H(s), y(t) \xleftrightarrow{L} Y(s), x(t) \xleftrightarrow{L} X(s)$$

$$H(s) = \frac{1}{s+a}; \quad Y(s) = \frac{1}{s+b} - \frac{1}{s+c} = \frac{s+c-s-b}{(s+b)(s+c)} = \frac{c-b}{(s+b)(s+c)}$$

$$\text{As } H(s) = \frac{Y(s)}{X(s)}, \quad X(s) = \frac{Y(s)}{H(s)}$$

$$\therefore X(s) = \frac{(c-b)(s+a)}{(s+b)(s+c)} = \frac{A}{s+b} + \frac{B}{s+c}$$

$$A = \left. \frac{(c-b)(s+a)}{(s+c)} \right|_{s=-b} = \frac{(c-b)(-b+a)}{(-b+c)} = a-b$$

$$B = \left. \frac{(c-b)(s+a)}{(s+b)} \right|_{s=-c} = \frac{(c-b)(-c+a)}{(-c+b)} = c-a$$

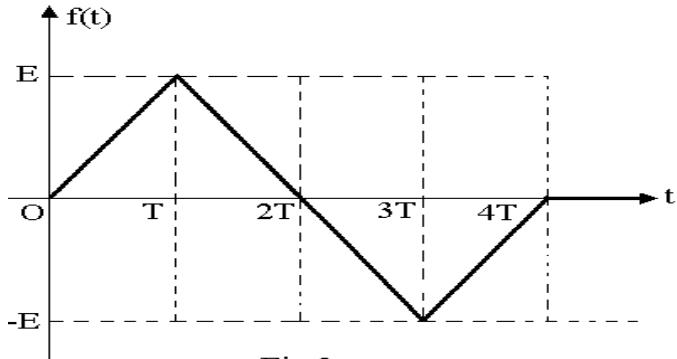
$$\therefore X(s) = \frac{a-b}{s+b} + \frac{c-a}{s+c}$$

$$x(t) = (a-b) e^{-bt} + (c-a) e^{-ct}$$

$$\therefore \text{The input } x(t) = [(a-b) e^{-bt} + (c-a) e^{-ct}] u(t)$$

- Q.7.** Write an expression for the waveform $f(t)$ shown in Fig. using only unit step function and powers of t . (3)

Ans:

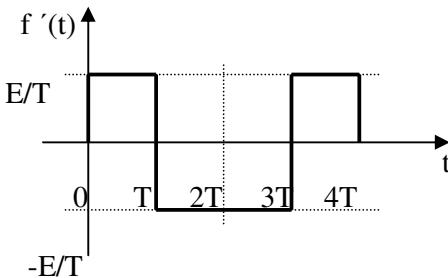


$$\therefore f(t) = \frac{E}{T} [t u(t) - 2(t-T) u(t-T) + 2(t-3T) u(t-3T) - (t-4T) u(t-4T)]$$

Q.8. For $f(t)$ of Q7, find and sketch $f'(t)$ (prime denotes differentiation with respect to t).

Ans:

$$f(t) = \frac{E}{T} [t u(t) - 2(t-T) u(t-T) + 2(t-3T) u(t-3T) - (t-4T) u(t-4T)]$$



$$\therefore f'(t) = \frac{E}{T} [u(t) - 2u(t-T) + 2u(t-3T) - u(t-4T)]$$

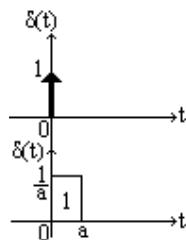
Q.9. Define a unit impulse function $\delta(t)$. (2)

Ans:

- Unit impulse function $\delta(t)$ is defined as:

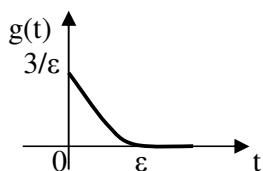
$$\left\{ \begin{array}{l} \delta(t) = 0, t \neq 0 \\ \int_{-\infty}^{+\infty} \delta(t) dt = 1 \end{array} \right.$$

It can be viewed as the limit of a rectangular pulse of duration a and height $1/a$ when $a \rightarrow 0$, as shown below.



Q.10. Sketch the function $g(t) = \frac{3}{\epsilon^3} (t-\epsilon)^2 [u(t) - u(t-\epsilon)]$ and show that (6)
 $g(t) \rightarrow \delta(t)$ as $\epsilon \rightarrow 0$.

Ans:



As $\epsilon \rightarrow 0$, duration $\rightarrow 0$, amplitude $\rightarrow \infty$
 $\int_0^\epsilon g(t) dt = 1$

Q.11. Show that if the FT of $x(t)$ is $X(j\omega)$, then the FT of $x\left(\frac{t}{a}\right)$ is $|a|X(ja\omega)$.

Ans:

$$x(t) \xleftrightarrow{\text{FT}} X(j\omega)$$

Let $x\left(\frac{t}{a}\right) \xleftrightarrow{\text{FT}} X_1(j\omega)$, then

$$X_1(j\omega) = \int_{-\infty}^{+\infty} x\left(\frac{t}{a}\right) e^{-j\omega t} dt \quad \text{Let } \underline{t} = a \quad \therefore dt = a d\underline{a}$$

$$= \int_{-\infty}^{+\infty} x(a) e^{-j\omega a \underline{a}} a d\underline{a} \text{ if } a > 0$$

$$- \int_{-\infty}^{+\infty} x(a) e^{-j\omega a \underline{a}} a d\underline{a} \text{ if } a < 0$$

$$\text{Hence } X_1(j\omega) = |a| \int_{-\infty}^{+\infty} x(a) e^{-j\omega a \underline{a}} d\underline{a} = |a| x(j\omega a)$$

Q.12. Solve, by using Laplace transforms, the following set of simultaneous differential equations for $x(t)$. (14)

Ans:

$$2x'(t) + 4x(t) + y'(t) + 7y(t) = 5u(t)$$

$$x'(t) + x(t) + y'(t) + 3y(t) = 5\delta(t)$$

The initial conditions are : $x(0-) = y(0-) = 0$.

$$2x'(t) + 4x(t) + y'(t) + 7y(t) = 5u(t)$$

$$x'(t) + x(t) + y'(t) + 3y(t) = 5\delta(t)$$

$$x(t) \xleftrightarrow{\text{L}} X(s), x'(t) \xleftrightarrow{\text{L}} sX(s), \delta(t) \xleftrightarrow{\text{L}} 1, u(t) \xleftrightarrow{\text{L}} \frac{1}{s}$$

(Given zero initial conditions)

$$\therefore 2sX(s) + 4X(s) + sY(s) + 7Y(s) = \underline{\frac{5}{s}}$$

$$sX(s) + X(s) + sY(s) + 3Y(s) = \underline{5}$$

$$(2s+4)X(s) + (s+7)Y(s) = \underline{\frac{5}{s}}$$

$$(s+1)X(s) + (s+3)Y(s) = \underline{5}$$

$$X(s) = \frac{\begin{vmatrix} 5 & s+7 \\ s & 3 \end{vmatrix}}{\begin{vmatrix} 2s+4 & s+7 \\ s+1 & s+3 \end{vmatrix}}$$

$$\text{Or, } X(s) = - \frac{5s + 35 - 5 - 15/s}{2s^2 + 6s + 4s + 12 - s^2 - 8s - 7}$$

$$= - \frac{5s^2 + 30s - 15}{s(s^2 + 2s + 5)} = - \frac{5}{s} \left(\frac{s^2 + 6s - 3}{s^2 + 2s + 5} \right) = \frac{A}{s} + \frac{Bs + C}{s^2 + 2s + 5}$$

$$\text{Then } A(s^2 + 2s + 5) + Bs^2 + Cs = -5(s^2 + 6s - 3)$$

$$\begin{aligned}\therefore A + B &= -5 \\ 2A + C &= -30 \\ 5A &= 15\end{aligned}$$

Thus $A = 3$, $B = -8$, $C = -36$ and we can write

$$\begin{aligned}X(s) &= \frac{3}{s} - \frac{8}{(s+1)^2 + 2^2} - 14 \frac{2}{(s+1)^2 + 2^2} \\ \therefore x(t) &= (3 - 8 e^{-t} \cos 2t - 14 e^{-t} \sin 2t) u(t)\end{aligned}$$

Q.13. Find the Laplace transform of $t \sin \omega_0 t u(t)$. (6)

Ans:

$$\sin(\omega_0 t) \xleftrightarrow[L]{} \frac{\omega_0}{s^2 + \omega_0^2}$$

$$\text{Using } t f(t) \xleftrightarrow[L]{} -\frac{d}{ds} [F(s)],$$

$$\begin{aligned}L[t \sin(\omega_0 t) u(t)] &= -\frac{d}{ds} \left[\frac{\omega_0}{s^2 + \omega_0^2} \right] \\ &= \left[\frac{0 - \omega_0(2s)}{(s^2 + \omega_0^2)^2} \right] = \frac{2\omega_0 s}{(s^2 + \omega_0^2)^2}\end{aligned}$$

Q.14. Find the inverse Laplace transform of $\frac{s-2}{s(s+1)^3}$. (8)

Ans:

$$F(s) = \frac{s-2}{s(s+1)^3} = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{(s+1)^2} + \frac{D}{(s+1)^3}$$

$$A = \left. \frac{s-2}{(s+1)^3} \right|_{s=0} = -2 \quad A(s+1)^3 + Bs(s+1)^2 + Cs(s+1) + Ds = s-2$$

$$D = \left. \frac{s-2}{s} \right|_{s=-1} = 3 \quad s^3 : A+B=0$$

$$B = 2$$

$$C = 2$$

$$A = -2$$

$$D = 3$$

$$\begin{aligned} F(s) &= \frac{-2}{s} + \frac{2}{s+1} + \frac{2}{(s+1)^2} + \frac{3}{(s+1)^3} \\ \therefore f(t) &= -2 + 2 e^{-t} + 2 t e^{-t} + \underline{\frac{3}{2} t^2 e^{-t}} \\ \therefore f(t) &= \frac{[-2 + e^{-t} (\underline{\frac{3}{2} t^2} + 2t + 2)]}{2} u(t) \end{aligned}$$

- Q.15.** Show that the difference equation $y(n) - \alpha y(n-1) = -\alpha x(n) + x(n-1)$ represents an all-pass transfer function. What is (are) the condition(s) on α for the system to be stable? (8)

Ans:

$$y(n) - \alpha y(n-1) = -\alpha x(n) + x(n-1)$$

$$Y(z) - \alpha z^{-1} Y(z) = -\alpha X(z) + z^{-1} X(z)$$

$$(1 - \alpha z^{-1}) Y(z) = (-\alpha + z^{-1}) X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{-\alpha + z^{-1}}{1 - \alpha z^{-1}} = \frac{1 - \alpha z}{z - \alpha}$$

$\text{Zero : } z = \frac{1}{\alpha}$ $\text{Pole : } z = \alpha$	As poles and zeros have reciprocal values, the transfer function represents an all pass filter system.
--	--

Condition for stability of the system :

For stability, the pole at $z = \alpha$ must be inside the unit circle, i.e. $|\alpha| < 1$.

- Q.16.** Give a recursive realization of the transfer function $H(z) = 1 + z^{-1} + z^{-2} + z^{-3}$ (6)

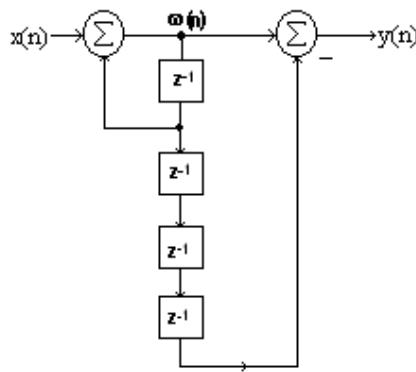
Ans:

$$H(z) = 1 + z^{-1} + z^{-2} + z^{-3} = \frac{1 - z^{-4}}{1 - z^{-1}} \left(\begin{array}{l} \text{Geometric series of 4 terms} \\ \text{First term = 1, Common ratio = } z^{-1} \end{array} \right)$$

As $H(z) = \frac{Y(z)}{X(z)}$, we can write

$$\therefore (1 - z^{-1}) Y(z) = (1 - z^{-4}) X(z) \text{ or } Y(z) = \frac{X(z)}{(1 - z^{-1})} (1 - z^{-4}) = W(z)(1 - z^{-4})$$

The realization of the system is shown below.



Q.17 Determine the z-transform of $x_1(n) = \alpha^n u(n)$ and $x_2(n) = -\alpha^n u(-n-1)$ and indicate their regions of convergence. (6)

Ans:

$$x_1(n) = \alpha^n u(n) \quad \text{and} \quad x_2(n) = -\alpha^n u(-n-1)$$

$$X_1(z) = \frac{1}{1-\alpha z^{-1}} \quad \text{RoC } |\alpha z^{-1}| < 1 \text{ i.e., } |z| > |\alpha|$$

$$\begin{aligned} X_2(z) &= \sum_{n=-\infty}^{-1} -\alpha^n z^{-n} \\ &= -\sum_{n=1}^{\infty} \alpha^{-n} z^n = -(\alpha^{-1}z + \alpha^{-2}z^2 + \alpha^{-3}z^3 + \dots) \\ &= -\alpha^{-1}z (1 + \alpha^{-1}z + \alpha^{-2}z^2 + \dots) \\ &= \frac{-\alpha^{-1}z}{1 - \alpha^{-1}z} = \frac{z}{z - \alpha} = \frac{1}{1 - \alpha z^{-1}} ; \quad \text{RoC } |\alpha^{-1}z| < 1 \text{ i.e., } |z| < |\alpha| \end{aligned}$$

Q.18. Determine the sequence $h(n)$ whose z-transform is

$$H(z) = \frac{1}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}, \quad |r| < 1. \quad (6)$$

Ans:

$$\begin{aligned} H(z) &= \frac{1}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}, \quad |r| < 1 \\ &= \frac{1}{(1 - r e^{j\theta} z^{-1})(1 - r e^{-j\theta} z^{-1})}, \quad |r| < 1 \\ &= \frac{A}{(1 - r e^{j\theta} z^{-1})} + \frac{B}{(1 - r e^{-j\theta} z^{-1})} \quad = \quad |r| < 1 \end{aligned}$$

$$\text{where } A = \frac{1}{(1-r e^{j\theta} z^{-1})} \Big|_{r e^{j\theta} z^{-1}=1} = \frac{1}{1 - e^{-j2\theta}}$$

$$B = \frac{1}{(1-r e^{j\theta} z^{-1})} \Big|_{r e^{-j\theta} z^{-1}=1} = \frac{1}{1 - e^{j2\theta}}$$

$$\therefore h(n) = \frac{1}{1 - e^{-j2\theta}} (r e^{j\theta})^n + \frac{1}{1 - e^{j2\theta}} (r e^{-j\theta})^n$$

$$\therefore h(n) = r^n \left[\frac{e^{jn\theta}}{1 - e^{-j2\theta}} + \frac{e^{-jn\theta}}{1 - e^{j2\theta}} \right] u(n)$$

$$= r^n \frac{e^{j(n+1)\theta} - e^{-j(n+1)\theta}}{e^{j\theta} - e^{-j\theta}} u(n)$$

$$= \frac{r^n \sin(n+1)\theta}{\sin\theta} u(n)$$

Q.19. Let the Z-transform of $x(n)$ be $X(z)$. Show that the z-transform of $x(-n)$ is $X\left(\frac{1}{z}\right)$. (2)

Ans:

$$x(n) \xleftrightarrow{Z} X(z) \quad \text{Let } y(n) = x(-n)$$

$$\text{Then } Y(z) = \sum_{n=-\infty}^{\infty} x(-n) z^{-n} = \sum_{r=-\infty}^{\infty} x(r) z^{+r} = \sum_{r=-\infty}^{\infty} x(r) (z^{-1})^{-1} = X(z^{-1})$$

Q.20. Find the energy content in the signal $x(n) = e^{-n/10} \sin\left(\frac{2\pi n}{4}\right)$. (7)

Ans:

$$x(n) = e^{-0.1n} \sin\left(\frac{2\pi n}{4}\right)$$

$$\text{Energy content } E = \sum_{n=-\infty}^{+\infty} |x^2(n)| = \sum_{n=-\infty}^{+\infty} e^{-0.2n} \left[\sin\left(\frac{2\pi n}{4}\right) \right]^2$$

$$E = \sum_{n=-\infty}^{+\infty} e^{-2n} \frac{\sin^2 \frac{n\pi}{2}}{2}$$

$$E = \sum_{n=-\infty}^{+\infty} e^{-2n} \frac{1 - \cos n\pi}{2}$$

$$= \frac{1}{2} \sum_{n=-\infty}^{+\infty} e^{-2n} [1 - (-1)^n]$$

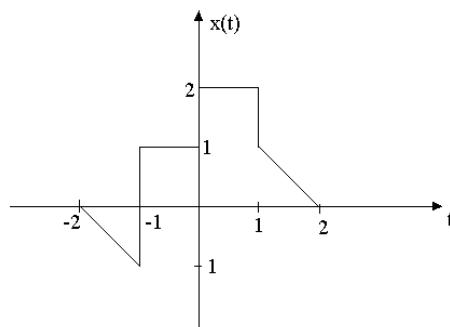
Now $1 - (-1)^n = \begin{cases} 2 & \text{for } n \text{ odd} \\ 0 & \text{for } n \text{ even} \end{cases}$

$$\text{Also Let } n = 2r + 1; \text{ then } E = \sum_{r=-\infty}^{\infty} e^{-2(2r+1)} = \sum_{r=-\infty}^{\infty} e^{-4r} e^{-2}$$

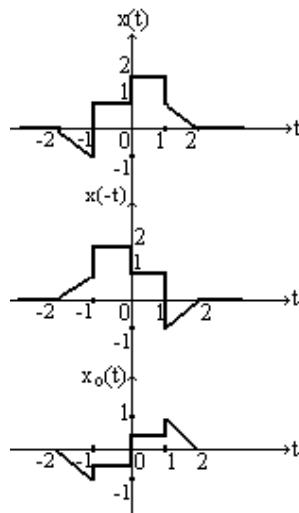
$$= e^{-2} \left[\sum_{r=0}^{\infty} e^{-4r} + \sum_{r=1}^{\infty} e^{-4r} \right] \quad \text{The second term in brackets goes to infinity. Hence } E \text{ is infinite.}$$

Q.21. Sketch the odd part of the signal shown in Fig. (3)

Ans:

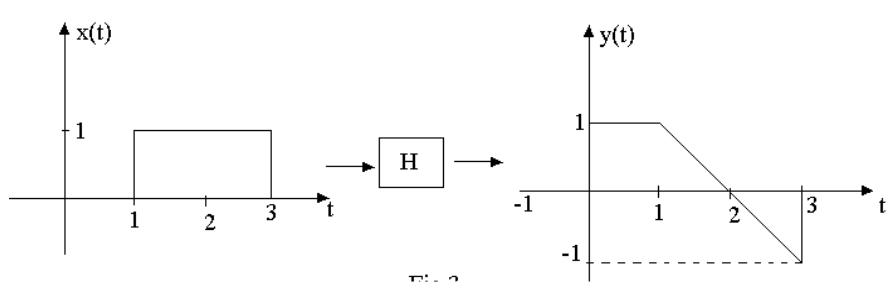


$$\text{Odd part } x_0(t) = \frac{x(t) - x(-t)}{2}$$



Q.22. A linear system H has an input-output pair as shown in Fig. Determine whether the system is causal and time-invariant. (4)

Ans



System is non-causal : the output $y(t)$ exists at $t = 0$ when input $x(t)$ starts only at $t = +1$.

System is time-varying : the expression for $y(t) = [u(t) - u(t-1)(t-1) + u(t-3)(t-3) - u(t-3)]$ shows that the system H has time varying parameters.

Q.23. Determine whether the system characterized by the differential equation

$$\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} + 2y(t) = x(t) \quad (4)$$

Ans:

$$\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} + 2y(t) = x(t)$$

$$y(t) \xleftrightarrow{L} Y(s); \quad x(t) \xleftrightarrow{L} X(s); \text{Zero initial conditions}$$

$$s^2 Y(s) - sY(s) + 2Y(s) = X(s)$$

$$\text{System transfer function } \frac{Y(s)}{X(s)} = \frac{1}{s^2 - s + 2} \text{ whose poles are in the right half plane.}$$

Hence the system is not stable.

Q.24 Determine whether the system $y(t) = \int_{-\infty}^t x(\tau) d\tau$ is invertible. (5)

Ans:

$$y(t) = \int_{-\infty}^t x(\tau) d\tau$$

Condition for invertibility: $H^{-1}H = I$ (Identity operator)

$$\left\{ \begin{array}{l} H \rightarrow \text{Integration} \\ H^{-1} \rightarrow \text{Differentiation} \end{array} \right.$$

$$x(t) \rightarrow y(t) = H\{x(t)\}$$

$$H^{-1}\{y(t)\} = H^{-1}H\{x(t)\} = x(t)$$

∴ The system is invertible.

Q.25 Find the impulse response of a system characterized by the differential equation $y'(t) + a y(t) = x(t)$. (5)

Ans:

$$y'(t) + a y(t) = x(t)$$

$$x(t) \xleftrightarrow{L} X(s), \quad y(t) \xleftrightarrow{L} Y(s), \quad h(t) \xleftrightarrow{L} H(s)$$

$sY(s) + aY(s) = X(s)$, assuming zero initial conditions

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s + a}$$

\therefore The impulse response of the system is $h(t) = e^{-at} u(t)$

Q.26. Compute the Laplace transform of the signal $y(t) = (1 + 0.5 \sin t) \sin 1000t$. (4)

Ans:

$$\begin{aligned} y(t) &= (1 + 0.5 \sin t) \sin 1000t \\ &= \sin 1000t + 0.5 \sin t \sin 1000t \\ &= \sin 1000t + 0.5 \left[\frac{\cos 999t - \cos 1001t}{2} \right] \\ &= \sin 1000t + 0.25 \cos 999t - 0.25 \cos 1001t \end{aligned}$$

$$\therefore Y(s) = \frac{1000}{s^2 + 1000^2} + 0.25 \frac{s}{s^2 + 999^2} - 0.25 \frac{s}{s^2 + 1001^2}$$

Q.27. Determine Fourier Transform $F(\omega)$ of the signal $f(t) = e^{-\alpha t} \cos(\omega t + \theta)$ and determine the value of $|F(\omega)|$. (7)

Ans:

We assume $f(t) = e^{-\alpha t} \cos(\omega t + \theta) u(t)$ because otherwise FT does not exist

$$f(t) \xrightarrow{\text{FT}} F(\omega) = \int_{-\infty}^{+\infty} e^{-\alpha t} \frac{e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)}}{2} e^{-j\omega t} dt$$

$$\begin{aligned} \therefore F(\omega) &= \frac{1}{2} \int_{-\infty}^{+\infty} [e^{-\alpha t} e^{-j\omega t} e^{j\omega t + j\theta} + e^{-\alpha t} e^{-j\omega t} e^{-j\omega t - j\theta}] dt \\ &= \frac{1}{2} \int_{-\infty}^{+\infty} [e^{-\alpha t + j\theta} + e^{-j\theta} e^{-(\alpha + 2j\omega)t}] dt \end{aligned}$$

$$\begin{aligned} |F(\omega)| &= \frac{1}{2} \left| e^{j\theta} \frac{e^{-\alpha}}{-\alpha} \right|_{0}^{+\infty} + e^{-j\theta} \frac{e^{-(\alpha+2j\omega)t}}{-(\alpha+2j\omega)} \Big|_0^\omega \\ &= \frac{1}{2} \left| \frac{1}{\alpha} e^{j\theta} + \frac{1}{\alpha+2j\omega} e^{-j\theta} \right| \end{aligned}$$

$$\therefore |F(\omega)| = \frac{1}{2} \left| \frac{(\alpha + 2j\omega) e^{j\theta} + \alpha e^{-j\theta}}{\alpha (\alpha + 2j\omega)} \right|$$

$$= \frac{1}{2} \left| \frac{2\alpha \cos \theta + 2j\omega e^{j\theta}}{\alpha (\alpha + 2j\omega)} \right|$$

$$= \left| \frac{\alpha \cos \theta + j \omega \cos \theta - j \omega \sin \theta}{\alpha (\alpha + 2j\omega)} \right|$$

$$\left| F(\omega) \right|^2 = \frac{\alpha^2 \cos^2 \theta + \omega^2 - 2\alpha\omega \sin \theta + \cos \theta}{\alpha^2 (\alpha^2 + 4\omega^2)}$$

$$= \frac{\omega^2 + \alpha^2 \cos^2 \theta - \alpha\omega \sin 2\theta}{\alpha^2 (\alpha^2 + 4\omega^2)}$$

- Q.28.** Determine the impulse response $h(t)$ and sketch the magnitude and phase response of the system described by the transfer function

(14)

$$H(s) = \frac{s^2 + \omega_0^2}{s^2 + \frac{\omega_0}{Q}s + \omega_0^2}.$$

Ans:

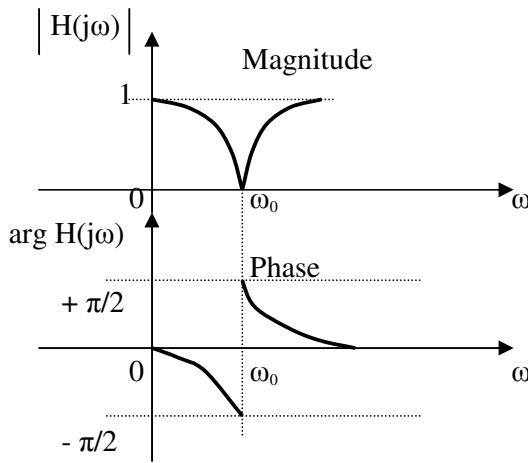
$$H(s) = \frac{s^2 + \omega_0^2}{s^2 + \frac{\omega_0}{Q}s + \omega_0^2}$$

$$H(j\omega) = \frac{(j\omega)^2 + \omega_0^2}{(j\omega)^2 + \frac{\omega_0}{Q}(j\omega) + \omega_0^2} = \frac{\omega_0^2 - \omega^2}{\omega_0^2 - \omega^2 + j\omega \frac{\omega_0}{Q}}$$

$$\therefore |H(j\omega)| = \sqrt{\left(\frac{\omega_0^2 - \omega^2}{\omega_0^2 - \omega^2 + \omega^2 \left[\frac{\omega_0}{Q} \right]} \right)^2}$$

$$\text{Arg } H(j\omega) = -\tan^{-1} \left(\frac{\omega \left[\frac{\omega_0}{Q} \right]}{\omega_0^2 - \omega^2} \right)$$

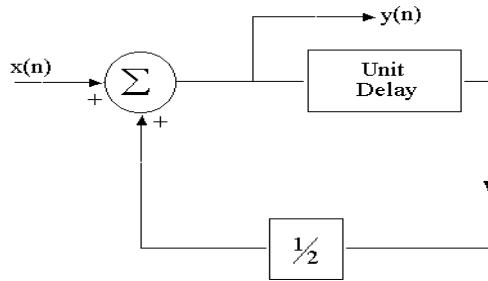
ω	$ H(j\omega) $	$\text{Arg } H(j\omega)$
0	1	0
∞	1	0
ω_{0-}	0	$-\pi/2$
ω_{0+}	0	$+\pi/2$



Q.29. Using the convolution sum, determine the output of the digital system shown in Fig. below.

Assume that the input sequence is $\{x(n)\} = \{3, -1, 3\}$ and that the system is initially at rest.

(5)



Ans:

$$x(n) = \{3, -1, 3\}, \text{ system at rest initially (zero initial conditions)}$$

\uparrow
 $n = 0$

$$x(n) = 3\delta(n) - \delta(n-1) + 3\delta(n-2)$$

$$X(z) = 3 - z^{-1} + 3z^{-2}$$

$$\text{Digital system: } y(n) = x(n) + \frac{1}{2} y(n-1)$$

$$\therefore Y(z) = \frac{X(z)}{1 - \frac{1}{2}z^{-1}} = \frac{3 - z^{-1} + 3z^{-2}}{1 - \frac{1}{2}z^{-1}} = -10 - 6z^{-1} + \frac{13}{1 - \frac{1}{2}z^{-1}}$$

by partial fraction expansion.

$$\text{Hence } y(n) = -10\delta(n) - 6\delta(n-1) + 13\left(\frac{1}{2}\right)^n u(n)$$

Q.30. Find the z-transform of the digital signal obtained by sampling the analog signal $e^{-4t} \sin 4t u(t)$ at intervals of 0.1 sec.

(6)

Ans:

$$x(t) = e^{-4t} \sin 4t u(t), \quad T = 0.1 \text{ s}$$

$$x(n) = x(t \rightarrow nT) = x(0.1n) = (e^{-0.4})^n \sin(0.4n)$$

$$x(n) \xleftrightarrow{Z} X(z)$$

$$x(n) = \sin \Omega n u(n) \xleftrightarrow{Z} \frac{z \sin \Omega}{z^2 - 2z \cos \Omega + 1}$$

$$\alpha = e^{-0.4} = 0.6703, \frac{1}{\alpha} = 1.4918$$

$$\Omega = 0.4 \text{ rad} = 22.92^\circ$$

$$\sin \Omega = 0.3894; \cos \Omega = 0.9211$$

$$\alpha^n x(n) \xleftrightarrow{z} X(z/\alpha)$$

$$\therefore X(z) = \frac{1.4918z(0.3894)}{(1.4918)^2 z^2 - 2(1.4918)z(0.9211) + 1}$$

$$X(z) = \frac{0.5809z}{2.2255 z^2 - 2.7482z + 1}$$

Q.31. An LTI system is given by the difference equation $y(n) + 2y(n-1) + y(n-2) = x(n)$.

- i. Determine the unit impulse response.
- ii. Determine the response of the system to the input $(3, -1, 3)$.

$$\begin{matrix} \uparrow \\ n=0 \end{matrix} \quad (4)$$

Ans:

$$y(n) + 2y(n-1) + y(n-2) = x(n)$$

$$Y(z) + 2z^{-1} Y(z) + z^{-2} Y(z) = X(z)$$

$$(1 + 2z^{-1} + z^{-2})Y(z) = X(z)$$

$$(i). H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 + 2z^{-1} + z^{-2}} = \frac{1}{(1 + z^{-1})^2} \quad (\text{Binomial expansion})$$

$$= 1 - 2z^{-1} + 3z^{-2} - 4z^{-3} + 5z^{-4} - 6z^{-5} + 7z^{-6} - \dots \dots \quad (\text{Binomial expansion})$$

$$\therefore h(n) = \delta(n) - 2\delta(n-1) + 3\delta(n-2) - \dots$$

$$\begin{matrix} \uparrow \\ n=0 \end{matrix} \quad = \{1, -2, 3, -4, 5, -6, 7, \dots\} \quad \text{is the impulse response.}$$

$$(ii). x(n) = \{3, -1, 3\}$$

$$\begin{matrix} \uparrow \\ n=0 \end{matrix}$$

$$= 3\delta(n) - \delta(n-1) + 3\delta(n-2)$$

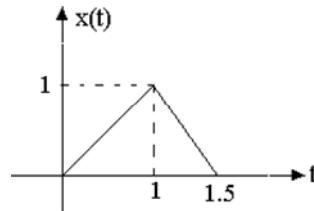
$$X(z) = 3 - z^{-1} + 3z^{-2}$$

$$\therefore Y(z) = X(z) \cdot H(z) = \frac{3 - z^{-1} + 3z^{-2}}{1 + 2z^{-1} + z^{-2}} = \frac{3(1 + 2z^{-1} + z^{-2}) - 7z^{-1}}{1 + 2z^{-1} + z^{-2}}$$

$$= 3 - 7 \frac{z^{-1}}{(1 + z^{-1})^2}$$

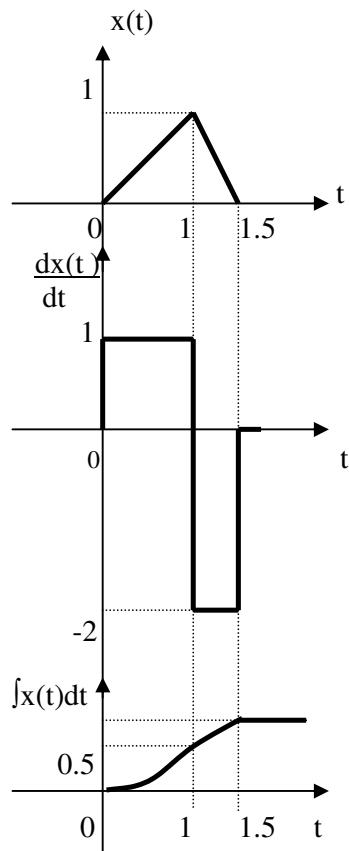
$$\therefore y(n) = 3\delta(n) + 7nu(n) \text{ is the required response of the system.}$$

$$x(t) = t u(t) - 3t u(t-1) + 2t u(t-1.5)$$



$$(1+4=)$$

Ans:



(i) $0 < t < 1$

$$y(t) = \left[\int_0^t t dt \right]_0^2 = t^2 \Big|_0^2 = 0.5 \text{ (Nonlinear)}$$

(ii) $1 < t < 1.5$

$$\begin{aligned}
 y(t) &= y(1) + \int_1^t (3-2t) dt \\
 &= 0.5 + (3t - t^2) \Big|_1^t = 0.5 + 3t - t^2 - 3 + 1 \\
 &= 3t - t^2 - 1.5 \quad (\text{Nonlinear})
 \end{aligned}$$

$$\text{For } t=1: y(1) = 3 - 1 - 1.5 = 0.5$$

$$(iii) \ t \geq 1.5 : y(1.5) = 4.5 - 2.25 - 1.5 = 0.75$$

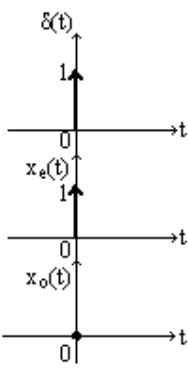
Q.33. Sketch the even and odd parts of

$$(1+2+3=6)$$

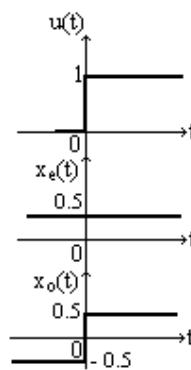
Ans:

$$\text{Even part } x_e(t) = \frac{x(t) + x(-t)}{2}$$

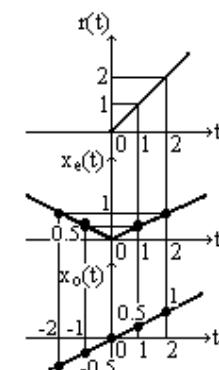
$$\text{Odd part } x_o(t) = \frac{x(t) - x(-t)}{2}$$



(i) unit impulse function

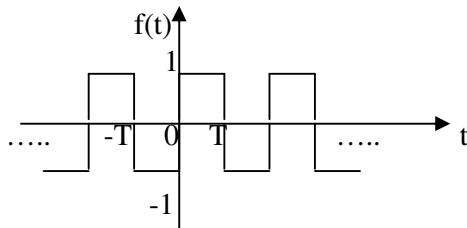


(ii) unit step function



(iii) unit ramp function

Q.34. Sketch the function $f(t) = u\left(\sin \frac{\pi t}{T}\right) - u\left(-\sin \frac{\pi t}{T}\right)$. (3)

Ans:

$$f(t) = \begin{cases} 1 & 0 < t \leq T, 2T < t \leq 3T \\ -1 & T < t \leq 2T, \dots \\ 3 & T < t < 4T, \dots \end{cases}$$

Q.35. Under what conditions, will the system characterized by $y(n) = \sum_{k=n_0}^{\infty} e^{-ak} x(n-k)$ be linear, time-invariant, causal, stable and memory less? (5)

Ans:

- y(n) is : linear and time invariant for all k
- causal if n_0 not less than 0.
- stable if $a > 0$
- memoryless if $k = 0$ only

Q.36. Let E denote the energy of the signal x (t). What is the energy of the signal x (2t)? (2)

Ans:

Given that

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$\text{To find } E^1 = \int_{-\infty}^{\infty} |x(2t)|^2 dt$$

$$\text{Let } 2t = r \text{ then } E^1 = \int_{-\infty}^{\infty} |x(r)|^2 \frac{dr}{2} = \frac{1}{2} \int_{-\infty}^{\infty} |x(r)|^2 dr = \frac{E}{2}$$

- Q.37.** $x(n)$, $h(n)$ and $y(n)$ are, respectively, the input signal, unit impulse response and output signal of a linear, time-invariant, causal system and it is given that $y(n-2) = x(n-n_1) * h(n-n_2)$, where $*$ denotes convolution. Find the possible sets of values of n_1 and n_2 . (3)

Ans:

$$\begin{aligned} y(n-2) &= x(n-n_1) * h(n-n_2) \\ \therefore z^{-2} Y(z) &= z^{-n_1} X(z) \cdot z^{-n_2} H(z) \\ z^{-2} H(z) X(z) &= z^{-(n_1+n_2)} X(z) H(z) \\ \therefore n_1+n_2 &= 2 \end{aligned}$$

Also, $n_1, n_2 \geq 0$, as the system is causal. So, the possible sets of values for n_1 and n_2 are:
 $\{n_1, n_2\} = \{(0,2), (1,1), (2,0)\}$

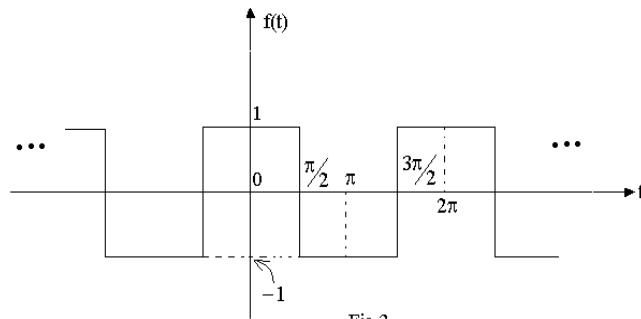
- Q.38.** Let $h(n)$ be the impulse response of the LTI causal system described by the difference equation $y(n) = a y(n-1) + x(n)$ and let $h(n) * h_1(n) = \delta(n)$. Find $h_1(n)$. (4)

Ans:

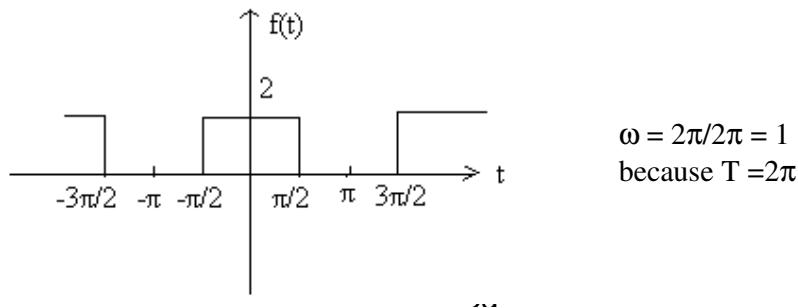
$$\begin{aligned} y(n) &= a y(n-1) + x(n) \quad \text{and} \quad h(n) * h_1(n) = \delta(n) \\ Y(z) &= az^{-1} Y(z) + X(z) \quad \text{and} \quad H(z) H_1(z) = 1 \\ H(z) &= \frac{Y(z)}{X(z)} = \frac{1}{1-az^{-1}} \quad \text{and} \quad H_1(z) = \frac{1}{H(z)} \\ \therefore H_1(z) &= 1-az^{-1} \quad \text{or} \quad h_1(n) = \delta(n) - a \delta(n-1) \end{aligned}$$

- Q.39.** Determine the Fourier series expansion of the waveform $f(t)$ shown below in terms of sines and cosines. Sketch the magnitude and phase spectra. **(10+2+2=14)**

Ans:



Define $g(t) = f(t) + 1$. Then the plot of $g(t)$ is as shown, below and,



$$g(t) = \begin{cases} 0 & -\pi < t < -\pi/2 \\ 2 & -\pi/2 < t < \pi/2 \\ 0 & \pi/2 < t < \pi \end{cases}$$

Let $g(t) = a_0 + \sum_{n=1}^{\infty} (a_n \cos nt + b_n \sin nt)$

Then $a_0 = \text{average value of } f(t) = 1$

$$a_n = \frac{2}{2\pi} \int_{-\pi/2}^{\pi/2} 2 \cos nt dt = \frac{2}{\pi} \frac{\sin nt}{n} \Big|_{-\pi/2}^{\pi/2} = 2/n \pi \cdot 2 \sin n \pi/2$$

$$= 4/n \pi \cdot \sin n \pi/2$$

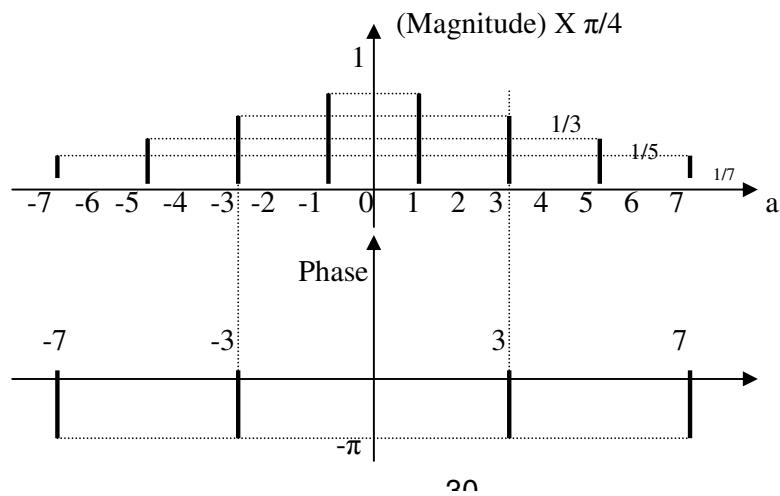
$$= \begin{cases} 0 & \text{if } n = 2, 4, 6, \dots \\ 4/n \pi & \text{if } n = 1, 5, 9, \dots \\ -4/n \pi & \text{if } n = 3, 7, 11, \dots \end{cases}$$

$$\text{Also, } b_n = \frac{2}{2\pi} \int_{-\pi/2}^{\pi/2} 2 \sin nt dt = \frac{4}{\pi} \frac{\cos nt}{n} \Big|_{-\pi/2}^{\pi/2} = 4/n \pi [\cos n \pi/2 - \cos n (-\pi/2)] = 0$$

Thus, we have $f(t) = -1 + g(t)$

$$\begin{aligned} &= \frac{4 \cos t}{\pi} - \frac{4 \cos 3t}{3\pi} + \frac{4 \cos 5t}{5\pi} - \dots \\ &= 4/\pi \{ \cos t - \cos 3t/3 + \cos 5t/5 - \dots \} \end{aligned}$$

spectra :



Q.40. Show that if the Fourier Transform (FT) of $x(t)$ is $X(\omega)$, then

$$\text{FT} \left[\frac{dx(t)}{dt} \right] = j\omega X(\omega).$$

Ans:

$$x(t) \xleftrightarrow{\text{FT}} X(j\omega) \text{ or } X(\omega)$$

$$\text{i.e., } x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$\therefore \frac{d}{dt} [x(t)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) j\omega e^{j\omega t} d\omega$$

$$\therefore \frac{d}{dt} [x(t)] \xleftrightarrow{\text{FT}} j\omega X(j\omega)$$

Q.41. Show, by any method, that $\text{FT} \left[\frac{1}{2} \right] = \pi \delta(\omega)$. (2)

Ans:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \pi \delta(\omega) e^{j\omega t} d\omega = \frac{1}{2} \quad \therefore X(j\omega) = \pi \delta(\omega)$$

$$\therefore \frac{1}{2} \xleftrightarrow{\text{FT}} \pi \delta(\omega)$$

Q.42 Find the unit impulse response, $h(t)$, of the system characterized by the relationship :

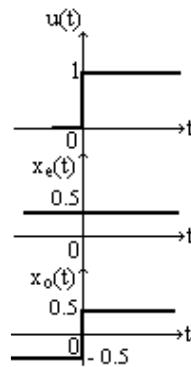
$$y(t) = \int_{-\infty}^t x(\tau) d\tau. \quad (3)$$

Ans:

$$y(t) = \int_{-\infty}^t \delta(\tau) d\tau = \begin{cases} 1, t \geq 0 = u(t) \\ 0, \text{ otherwise} \end{cases}$$

Q.43. Using the results of parts (a) and (b), or otherwise, determine the frequency response of the system of part (c).

Ans:



As shown in the figure, $u(t) = 1/2 + x(t)$

$$\text{where } x(t) = \begin{cases} 0.5, & t > 0 \\ -0.5, & t < 0 \end{cases}$$

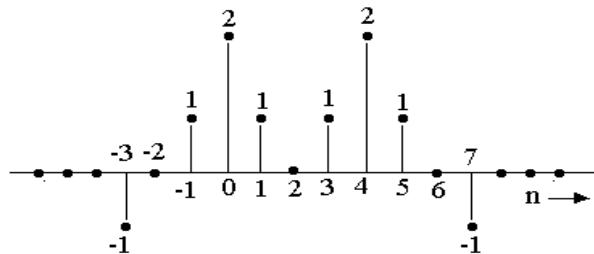
$\therefore dx/dt = \delta(t)$ By (a) $\text{FT}[\delta(t)] = j\omega X(\omega)$

$\therefore X(\omega) = 1/j\omega$. Also $\text{FT}[1/2] = \pi\delta(\omega)$

Therefore $\text{FT}[u(t)] = H(j\omega) = \pi\delta(\omega) + 1/j\omega$.

Q.44. Let $X(e^{j\omega})$ denote the Fourier Transform of the signal $x(n)$ shown below .(2+2+3+5+2=14)

Ans:



Without explicitly finding out $X(e^{j\omega})$, find the following :-

(i) $X(1)$

(ii) $\int_{-\pi}^{\pi} X(e^{j\omega}) d\omega$

(iii) $X(-1)$

(iv) the sequence $y(n)$ whose Fourier Transform is the real part of $X(e^{j\omega})$.

(v) $\int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega$.

Ans:

$$X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} x(n) e^{-j\omega n}$$

$$(i) X(1) = X(e^{j0}) = \sum_{-\infty}^{\infty} x(n) = -1 + 1 + 2 + 1 + 1 + 2 + 1 - 1 = 6$$

$$(ii) x(n) = \frac{1}{2\pi} \int_{-\pi}^{+\pi} X(e^{j\omega}) e^{j\omega n} d\omega ; \int_{-\pi}^{\pi} X(e^{j\omega}) d\omega = 2\pi x(0) = 4\pi$$

$$(iii) X(-1) = X(e^{j\pi}) = \sum_{n=-\infty}^{+\infty} x(n) (-1)^n = 1 + 0 - 1 + 2 - 1 + 0 - 1 + 2 - 1 + 0 + 1 = 2$$

$$(iv) \text{Real part } X(e^{j\omega}) \longleftrightarrow x_e(n) = \frac{x(n) + x(-n)}{2}$$

$$y(n) = x_e(n) = 0, \quad n < -7, n > 7$$

$$y(7) = \frac{1}{2} x(7) = \frac{-1}{2} = y(-7)$$

$$y(6) = \frac{1}{2} x(6) = 0 = y(-6)$$

$$y(5) = \frac{1}{2} x(5) = \frac{1}{2} = y(-5)$$

$$y(4) = \frac{1}{2} x(4) = 2 = y(-4)$$

$$y(3) = \frac{1}{2} [x(3) + x(-3)] = 0 = y(-3)$$

$$y(2) = \frac{1}{2} [x(2) + x(-2)] = 0 = y(-2)$$

$$y(1) = \frac{1}{2} [y(1) + y(-1)] = 1 = y(-1)$$

$$y(0) = \frac{1}{2} [y(0) + y(0)] = 2$$

(v) Parseval's theorem:

$$\int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega = 2\pi \sum_{n=-\infty}^{\infty} |x(n)|^2 = 2\pi(1 + 1 + 4 + 1 + 1 + 4 + 1 + 1) = 28\pi$$

Q.45 If the z-transform of x (n) is X(z) with ROC denoted by R_x, find the

$$\text{z-transform of } y(n) = \sum_{k=-\infty}^n x(k) \text{ and its ROC.} \quad (4)$$

Ans:

$$\begin{aligned} x(n) &\longleftrightarrow X(z), \quad \text{RoC } R_x \\ y(n) &= \sum_{k=-\infty}^n x(k) = \sum_{k=\infty}^0 x(n-k) = \sum_{k=0}^{\infty} x(n-k) \\ \therefore Y(z) &= X(z) \underbrace{\sum_{k=0}^{\infty} z^{-k}}_{1-z^{-1}} = \frac{X(z)}{1-z^{-1}}, \text{ RoC at least } R_x \cap (|z| > 1) \end{aligned}$$

Geometric series

- Q.46 (i)** $x(n)$ is a real right-sided sequence having a z-transform $X(z)$. $X(z)$ has two poles, one of which is at $a e^{j\phi}$ and two zeros, one of which is at $r e^{-j\theta}$. It is also known that $\sum x(n) = 1$. Determine $X(z)$ as a ratio of polynomials in z^{-1} . (6)
- (ii) If $a = \frac{1}{2}$, $r = 2$, $\theta = \phi = \pi/4$ in part (b) (i), determine the magnitude of $X(z)$ on the unit circle. (4)

Ans:

$$\text{(i) } x(n) : \text{real, right-sided sequence} \quad \xleftrightarrow{z} X(z)$$

$$\begin{aligned} X(z) &= K \frac{(z - re^{j\theta})(z - re^{-j\theta})}{(z - ae^{j\phi})(z - ae^{-j\phi})} ; \sum x(n) = X(1) = 1 \\ &= K \frac{z^2 - zr(e^{j\theta} + e^{-j\theta}) + r^2}{z^2 - za(e^{j\Phi} + e^{-j\Phi}) + a^2} \\ &= K \frac{1 - 2r \cos\theta z^{-1} + r^2 z^{-2}}{1 - 2a \cos\Phi z^{-1} + a^2 z^{-2}} = K \cdot \frac{N(z^{-1})}{D(z^{-1})} \end{aligned}$$

$$\text{where } K \cdot \frac{1 - 2r \cos\theta + r^2}{1 - 2a \cos\Phi + a^2} = X(1) = 1$$

$$\text{i.e., } K = \frac{1 - 2a \cos\Phi + a^2}{1 - 2r \cos\theta + r^2}$$

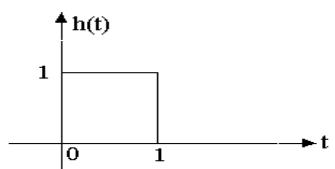
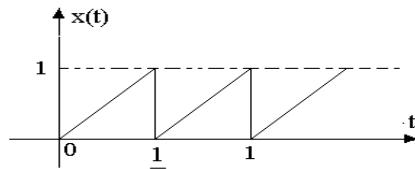
$$\text{(ii) } a = \frac{1}{2}, r = 2, \theta = \Phi = \pi/4 ; K = \frac{1 - 2(\frac{1}{2})(1/\sqrt{2}) + \frac{1}{4}}{1 - 2(2)(1/\sqrt{2}) + 4} = 0.25$$

$$X(z) = (0.25) \cdot \frac{1 - 2(2)(1/\sqrt{2}) z^{-1} + 4z^{-2}}{1 - 2(2)(1/\sqrt{2}) z^{-1} + \frac{1}{4} z^{-2}}$$

$$\begin{aligned} &= (0.25) \frac{1 - 2\sqrt{2} z^{-1} + 4z^{-2}}{1 - (1/\sqrt{2}) z^{-1} + \frac{1}{4} z^{-2}} \implies X(e^{j\omega}) = (0.25) \frac{1 - 2\sqrt{2} e^{-j\omega} + 4 e^{-2j\omega}}{1 - (1/\sqrt{2}) e^{-j\omega} + \frac{1}{4} e^{-2j\omega}} \\ &= \frac{-2\sqrt{2} + e^{j\omega} + 4 e^{-j\omega}}{-2\sqrt{2} + 4e^{j\omega} + e^{-j\omega}} \\ &\therefore |X(e^{j\omega})| = 1 \end{aligned}$$

Q.47 Determine, by any method, the output $y(t)$ of an LTI system whose impulse response $h(t)$ is of the form shown in fig(a). to the periodic excitation $x(t)$ as shown in fig(b).

(14)

Ans:**Fig(a)****Fig(b)**

$$h(t) = u(t) - u(t-1) \Rightarrow H(s) = \frac{1 - e^{-s}}{s}$$

First period of $x(t)$, $x_T(t) = 2t [u(t) - u(t - 1/2)]$

$$= 2[t u(t) - (t-1/2) u(t-1/2) - 1/2 u(t-1/2)]$$

$$\therefore X_T(s) = 2[1/s^2 - e^{-s/2} / s^2 - 1/2 e^{-s/2} / s]$$

$$X(s) = X_T(s) / 1 - e^{-s/2}$$

$$Y(s) = \frac{1 - e^{-s}}{s} \cdot \frac{1}{1 - e^{-s/2}} 2 \left(\frac{1 - e^{-s/2} - 0.5s e^{-s/2}}{s^2} \right)$$

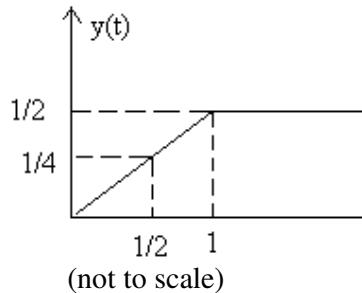
$$= \frac{2}{s^3} (1 + e^{-s/2}) [1 - e^{-s/2} - 0.5s e^{-s/2}]$$

$$= \frac{2}{s^3} (1 - e^{-s} - 0.5s(e^{-s/2} + e^{-s}))$$

$$= 2 \frac{1 - e^{-s}}{s^3} - \frac{e^{-s/2} + e^{-s}}{s^2}$$

$$\text{Therefore } y(t) = t^2 u(t) - (t-1)^2 u(t-1) - \left(t - \frac{1}{2} \right) u\left(t + \frac{1}{2} \right) - (t-1)u(t-1)$$

This gives $y(t) = \begin{cases} t^2 & 0 < t < 1/2 \\ t^2 - t + 1/2 & 1/2 < t < 1 \\ 1/2 & t > 1 \end{cases}$



Q.48 Obtain the time function $f(t)$ whose Laplace Transform is $F(s) = \frac{s^2 + 3s + 1}{(s+1)^3(s+2)^2}$.

Ans:

$$F(s) = \frac{s^2 + 3s + 1}{(s+1)^3(s+2)^2} = \frac{A}{(s+1)} + \frac{B}{(s+1)^2} + \frac{C}{(s+1)^3} + \frac{D}{(s+2)} + \frac{E}{(s+2)^2}$$

$$A(s+2)^2(s+1)^2 + B(s+2)^2(s+1) + C(s+2)^2 + D(s+1)^3(s+2) + E(s+1)^3 = s^2 + 3s + 1$$

$$C = \frac{s^2 + 3s + 1}{(s+2)^2} \Big|_{s=-1} = \frac{1-3+1}{1} = -1$$

$$C = -1$$

$$E = \frac{s^2 + 3s + 1}{(s+1)^3} \Big|_{s=-2} = \frac{4-6+1}{-1} = 1$$

$$E = 1$$

$$\begin{aligned} A(s^2 + 3s + 2)^2 + B(s^2 + 4s + 4)(s+1) + C(s^2 + 4s + 4) + D(s^3 + 3s^2 + 3s + 1)(s+2) + E(s^3 + 3s^2 + 3s + 1) \\ = s^2 + 3s + 1 \end{aligned}$$

$$\begin{aligned} A(s^4 + 6s^3 + 13s^2 + 12s + 4) + B(s^3 + 5s^2 + 8s + 4) + C(s^2 + 4s + 4) + D(s^4 + 5s^3 + 9s^2 + 7s + 2) + \\ E(s^3 + 3s^2 + 3s + 1) = s^2 + 3s + 1 \end{aligned}$$

$$s^4 : A + D = 0$$

$$s^3 : 6A + B + 5D + E = 0 ; A + B + 1 = 0 \quad \text{as } 5(A + D) = 0, E = 1$$

$$s^2 : 13A + 5B + C + 9D + 3E = 1 ; 4A + 5B + 1 = 0 \quad \text{as } 9(A + D) = 0, C = -1, E = 1$$

$$s^1 : 12A + 8B + 4C + 7D + 3E = 3 ; 5A + 8B - 4 = 0 \quad \text{as } 7(A + D) = 0, C = -1, E = 1$$

$$s^0 : 4A + 4B + 4C + 2D + E = 1$$

$$A + B = -1 ; 4(A + B) + B + 1 = 0 \text{ or } -4 + B + 1 = 0 \quad \text{or}$$

$$B = 3$$

$$A = -4$$

$$\therefore A = -1 - 3 = -4$$

$$A + D = 0 \text{ or } D = -A = 4$$

$$D = 4$$

$$\therefore F(s) = \frac{-4}{(s+1)} + \frac{3}{(s+1)^2} + \frac{-1}{(s+1)^3} + \frac{4}{(s+2)} + \frac{1}{(s+2)^2}$$

$$\therefore f(t) = L^{-1}[F(s)] = -4e^{-t} + 3t e^{-t} - t^2 e^{-t} + 4e^{-2t} + t e^{-2t} = [e^{-t}(-4 + 3t - t^2) + e^{-2t}(4 + t)] u(t)$$

$$\therefore f(t) = [e^{-t}(-4 + 3t - t^2) + e^{-2t}(4 + t)] u(t)$$

Q.49 Define the terms variance, co-variance and correlation coefficient as applied to random variables.

Ans:

Variance of a random variable X is defined as the second central moment

$E[(X-\mu_x)]^n$, n=2, where central moment is the moment of the difference between a random variable X and its mean μ_x i.e.,

$$\sigma_x^2 = \text{var } [X] = \int_{-\infty}^{+\infty} (x - \mu_x)^2 f_x(x) dx$$

Co-variance of random variables X and Y is defined as the joint moment:

$$\sigma_{XY} = \text{cov } [XY] = E[\{X-E[X]\}\{Y-E[Y]\}] = E[XY]-\mu_x\mu_y$$

where $\mu_x = E[X]$ and $\mu_y = E[Y]$.

Correlation coefficient ρ_{XY} of X and Y is defined as the co-variance of X and Y normalized

w.r.t $\sigma_x\sigma_y$:

$$\rho_{XY} = \frac{\text{cov } [XY]}{\sigma_x\sigma_y} = \frac{\sigma_{XY}}{\sigma_x\sigma_y}$$